

A field-data case study of extrapolated full-waveform inversion

Hongyu Sun

Graduate Student, Dept. of Earth, Atmospheric, and Planetary Sciences

In collaboration with

Rami Nammour, Christian Rivera, Paul Williamson, and Laurent Demanet

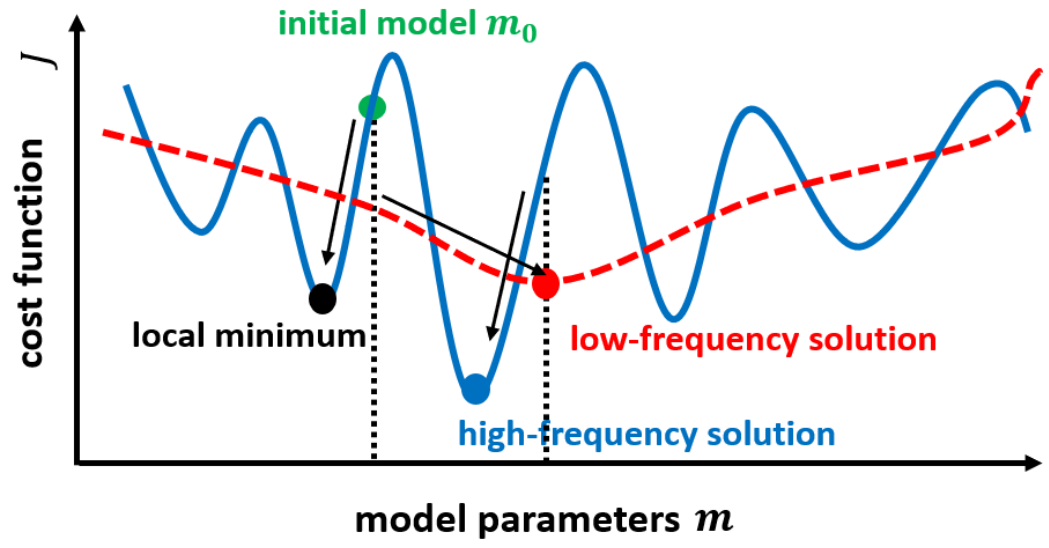
May 25, 2022

Thank TotalEnergies for permission to publish the work.



Extrapolated full-waveform inversion with deep learning

■ Cycle-skipping problem of FWI



■ Low-frequency extrapolation

- Signal processing
Hu, 2014; Li and Demanet, 2016
- Deep learning
Sun and Demanet, 2018; Jin et al., 2018; Ovcharenko et al., 2018;

true low-freq	good initial model	full-waveform inversion (FWI) video
No	No	
No	Yes	
No	No	with extrapolated < 0.6 Hz low-frequency data



Related contributions and challenges on field data

Field-data examples:

- Probably insufficient accuracy for full-waveform inversion
 - *Wang et al., 2020, SEG Technical Program Expanded Abstracts 2020*
 - ...
- Training on real data (collected from the same region as the test data)
 - *Aharchaou and Baumstein, 2020, The Leading Edge*
 - *Zhang et al., 2021, IEEE Geoscience and Remote Sensing Letters*
- Training on synthetic data
 - *Fang et al., 2020, Geophysics*
 - *Ovcharenko, 2021, KAUST Ph.D. thesis*

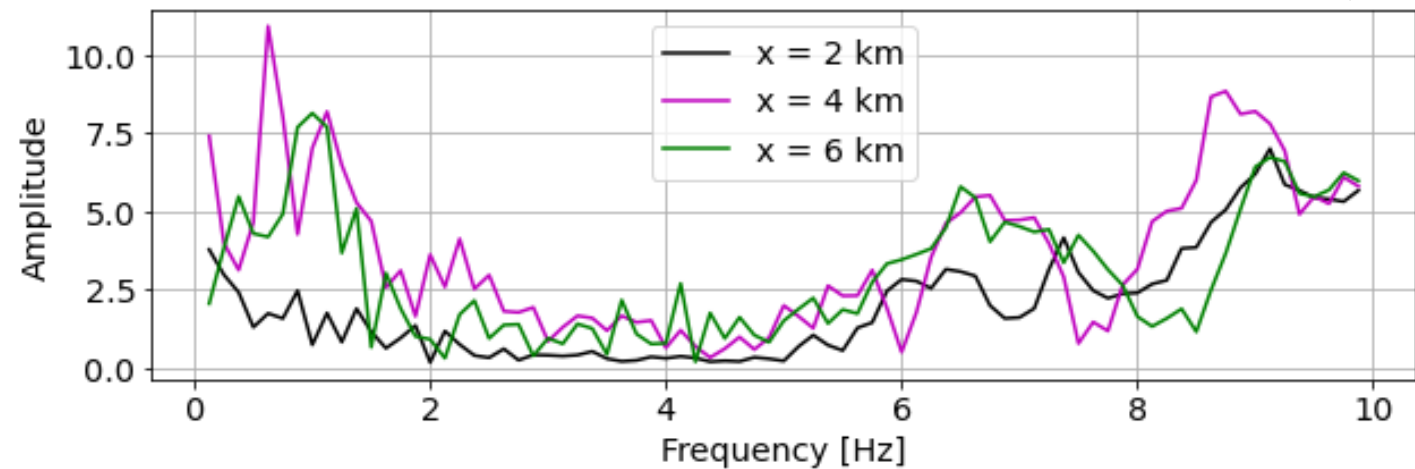
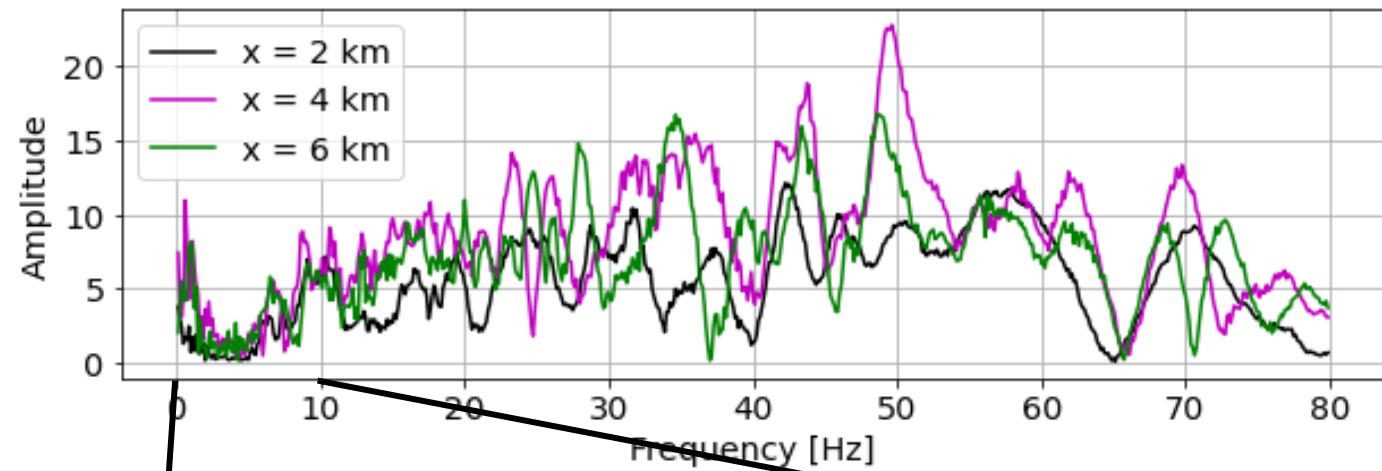
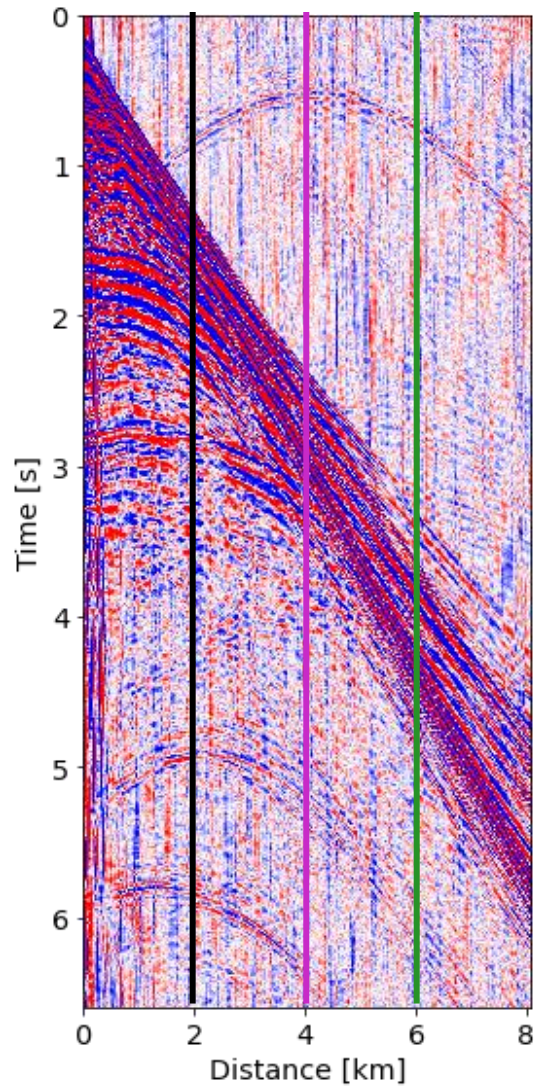
Challenges:

- Unavailability of real low-frequency data for training, in particular < 2 Hz
- Poor generalization from synthetic to real data

Our strategy: Semi-supervised learning with real data without real labels

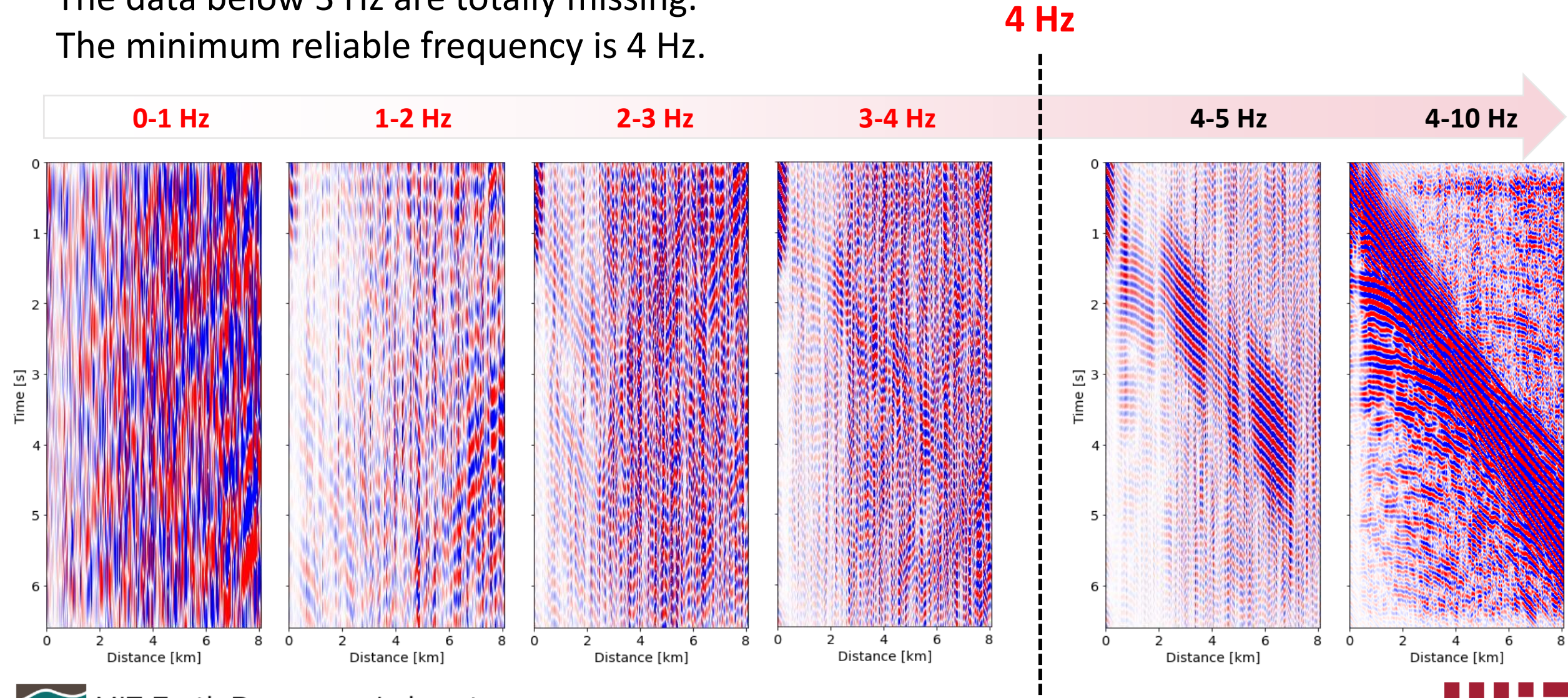


Field raw data in the time and frequency domain



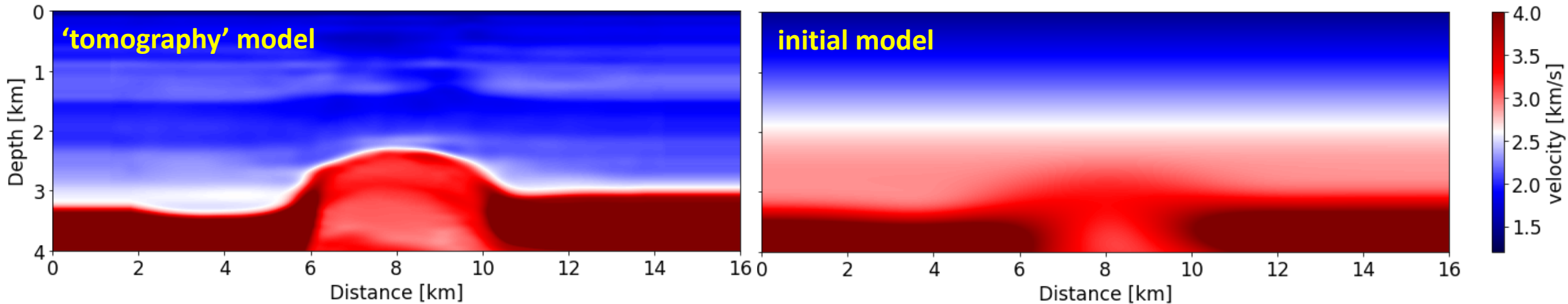
Field raw data in different frequency bands

The data below 3 Hz are totally missing.
The minimum reliable frequency is 4 Hz.

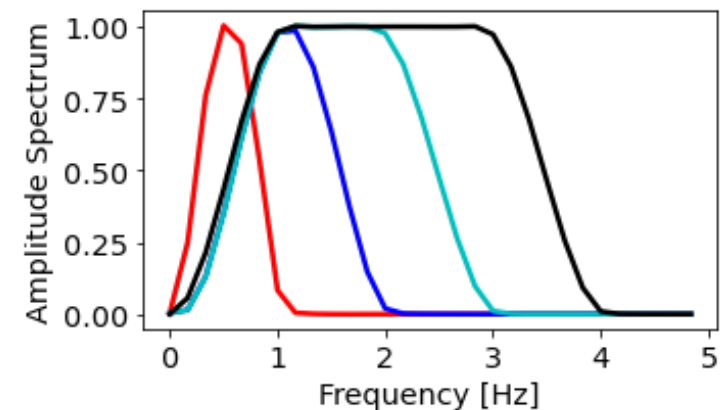
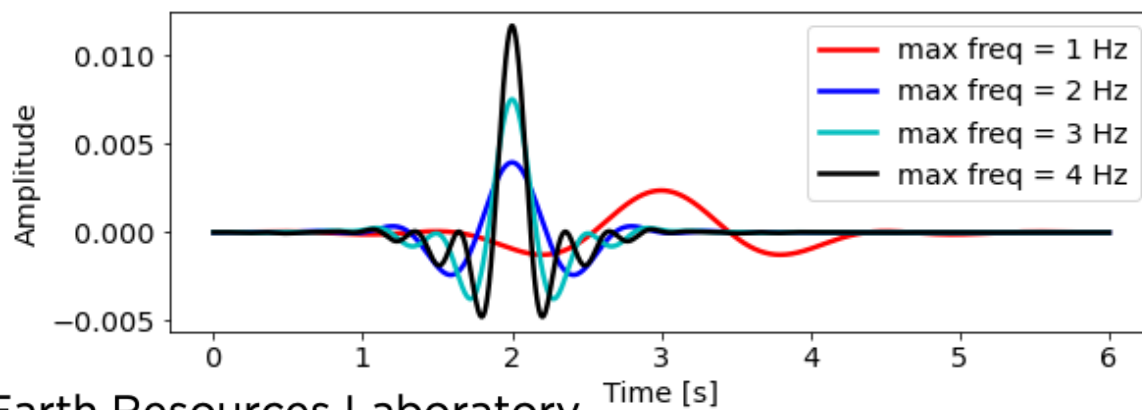


Determination of starting frequency

- Starting from the given initial model, how low should the starting frequency be to avoid the cycle-skipping problem?



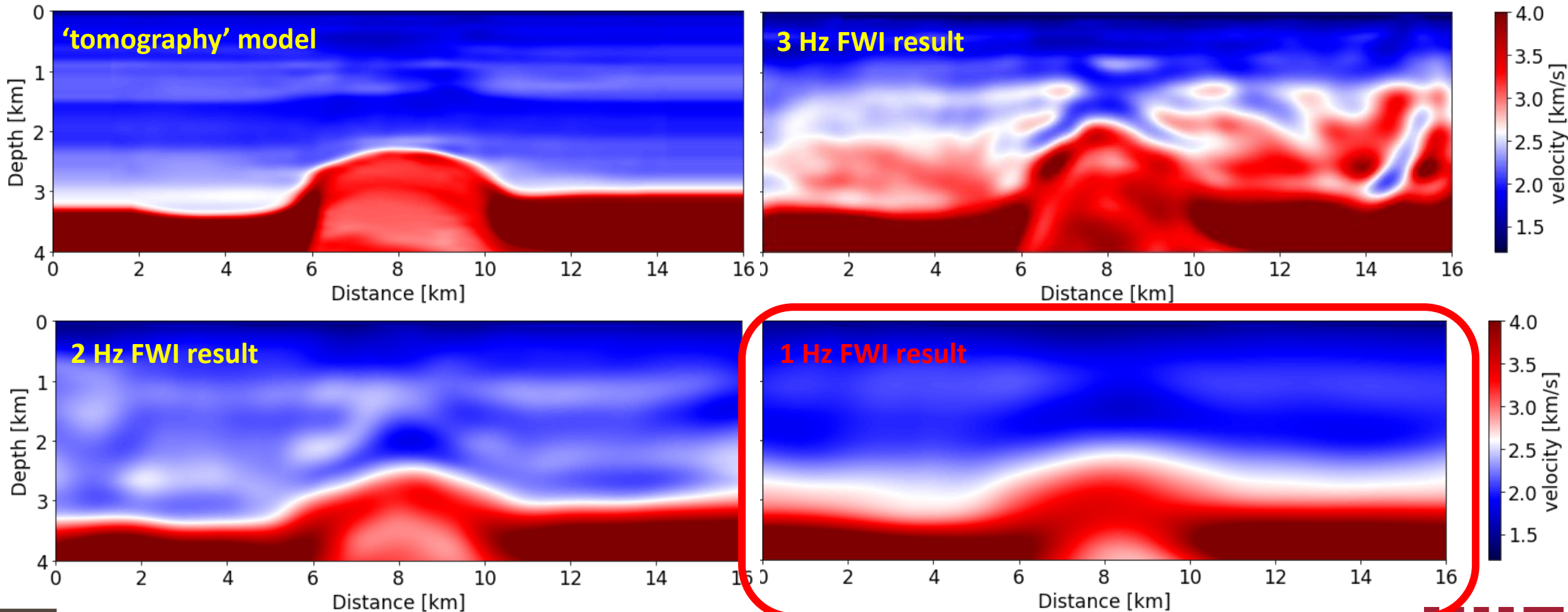
- Simulate low-frequency data on the "tomography" model



Determination of starting frequency

1 Hz

- Starting from the given initial model, how low should the starting frequency be to avoid the cycle-skipping problem?



Learning with real data without real labels

■ Cycle-Consistent Adversarial Networks (**forward cycle**)

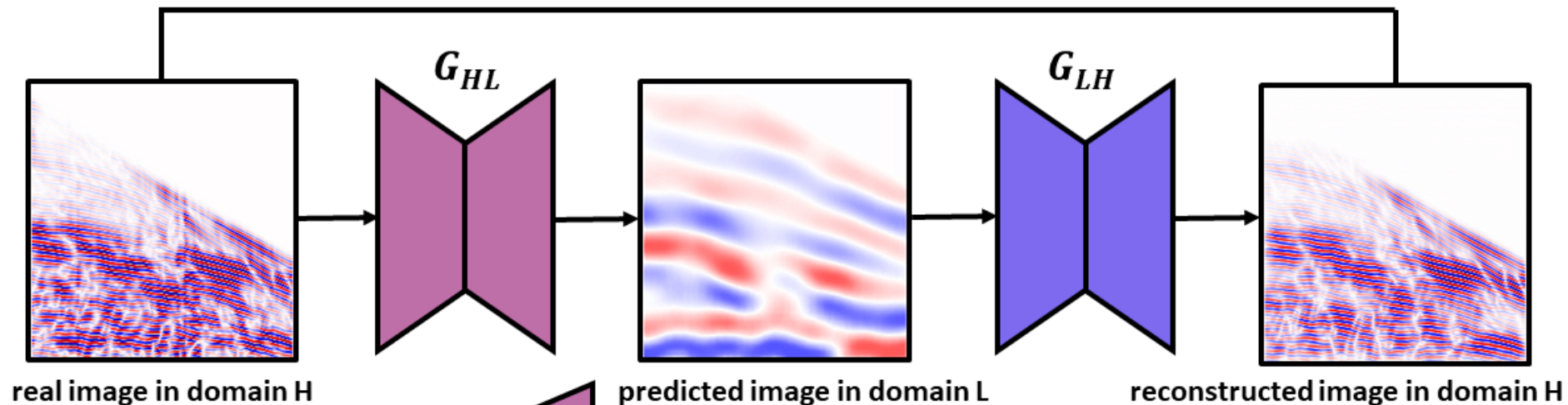
cycle-consistency loss

$$L(\mathbf{G}_{HL}, \mathbf{D}_L, H, L) =$$

$$\lambda_1 L_{cycle}(\mathbf{G}_{HL}, \mathbf{G}_{LH}, H)$$

$$\lambda_2 L_{GAN}(\mathbf{G}_{HL}, \mathbf{D}_L, H)$$

$$\lambda_3 L_{identity}(\mathbf{G}_{HL}, L)$$



reference or predicted ?

\mathbf{D}_L

(Sun, Nammour, Rivera, Williamson, and Demanet, 2022, under review)

$$L_{disc}(\mathbf{G}_{HL}, \mathbf{D}_L, H, L)$$

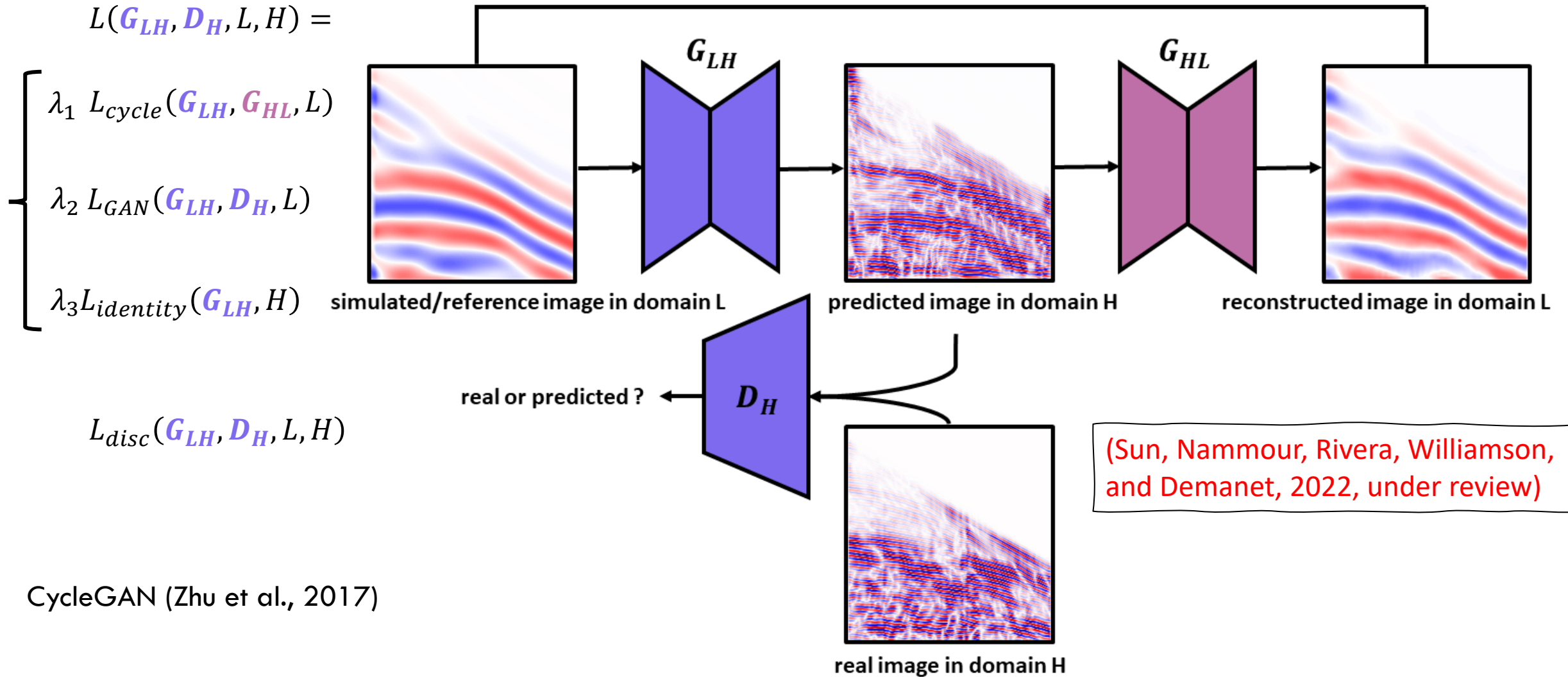
CycleGAN (Zhu et al., 2017)

simulated/reference image in domain L



Learning with real data without real labels

■ Cycle-Consistent Adversarial Networks (**backward cycle**) cycle-consistency loss

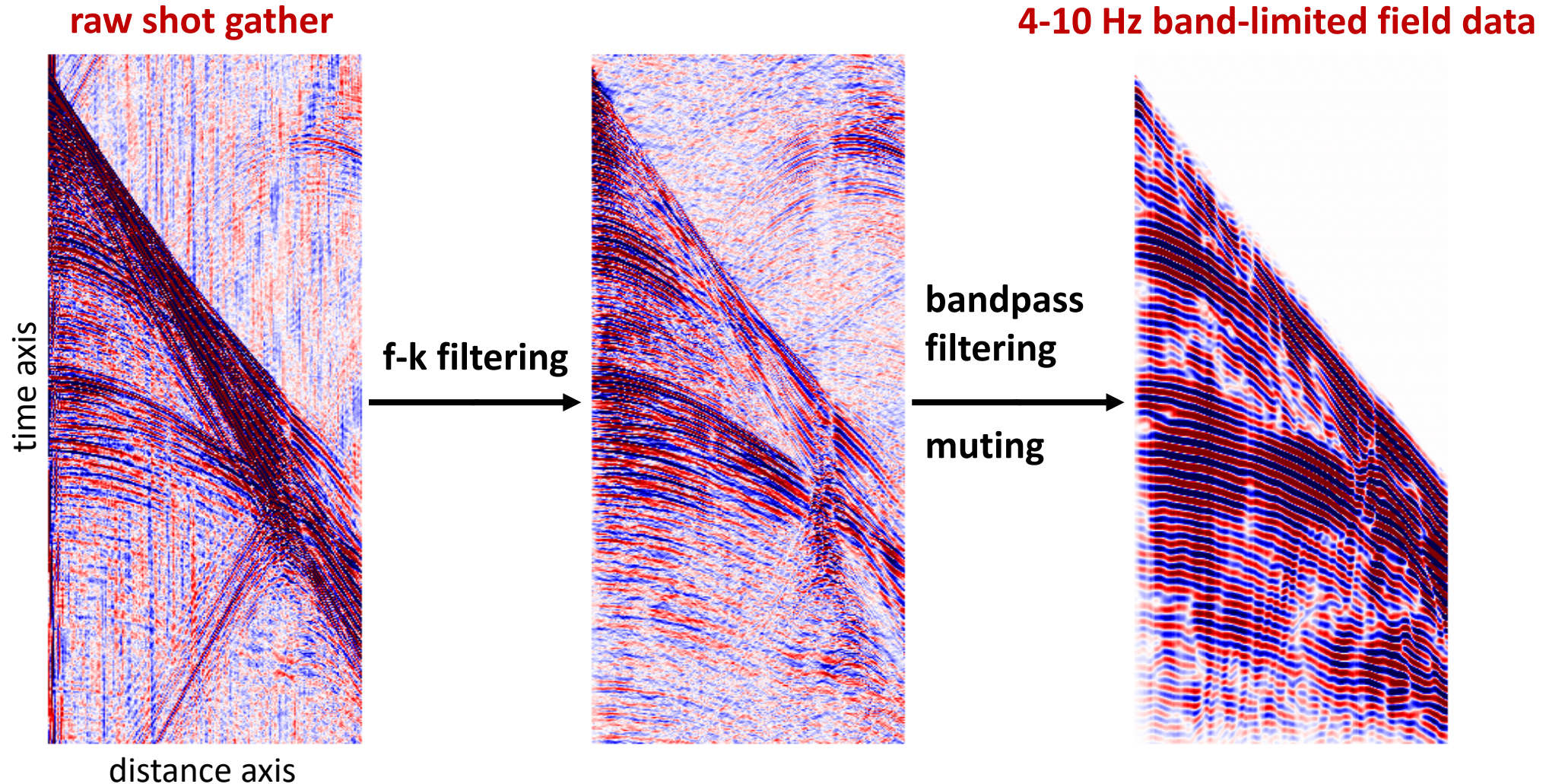


CycleGAN (Zhu et al., 2017)



Training data preparation for the field data

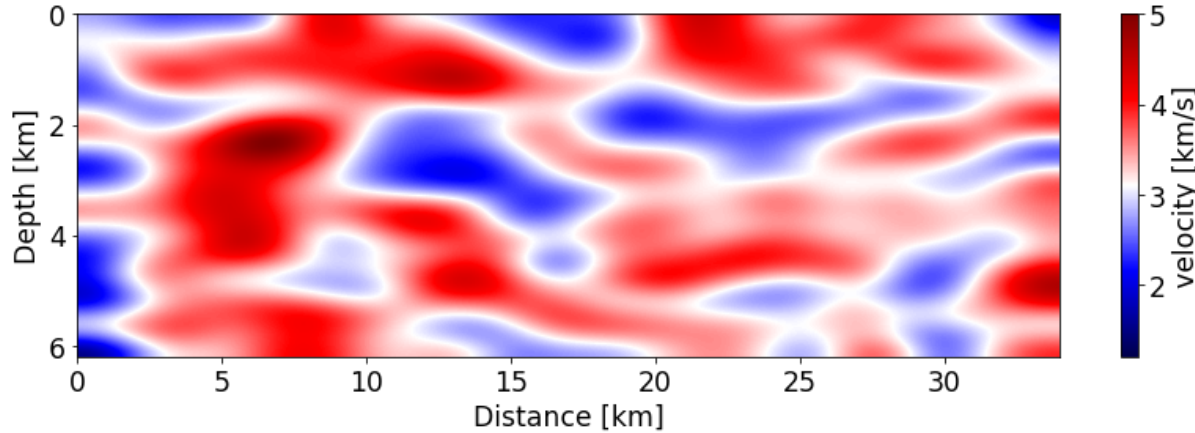
- Preprocess field data for 4-10 Hz band-limited data as image domain H



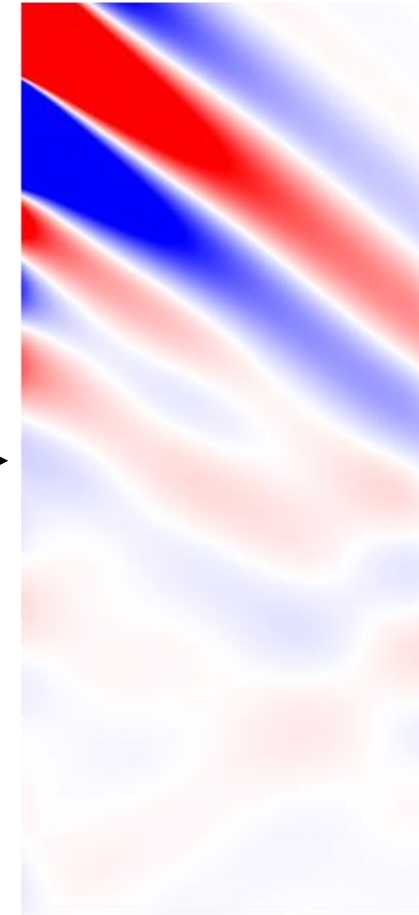
Training data preparation for the field data

- Simulate synthetic low-frequency data as image domain L

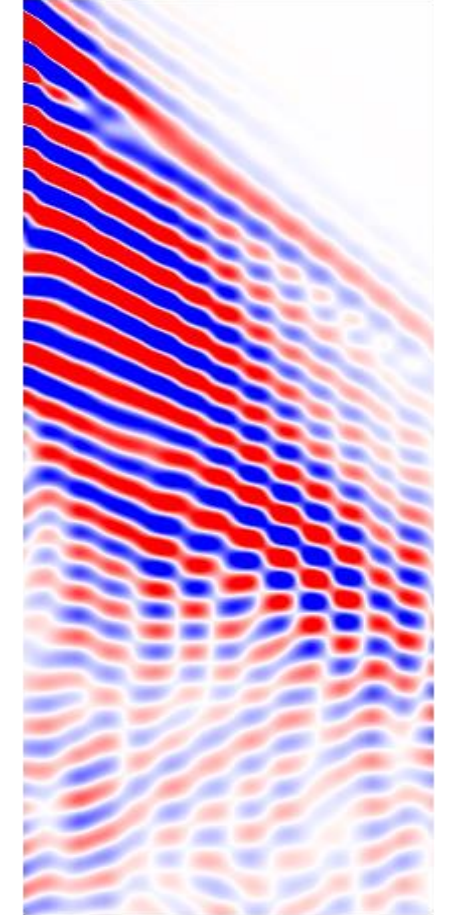
generation of a training model



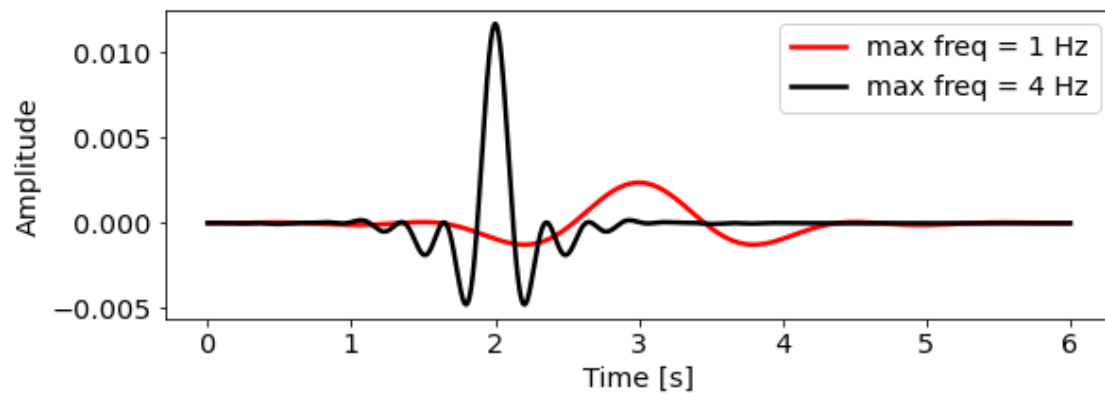
synthetic 0-1 Hz data



synthetic 0-4 Hz data



generation of low-frequency source wavelets

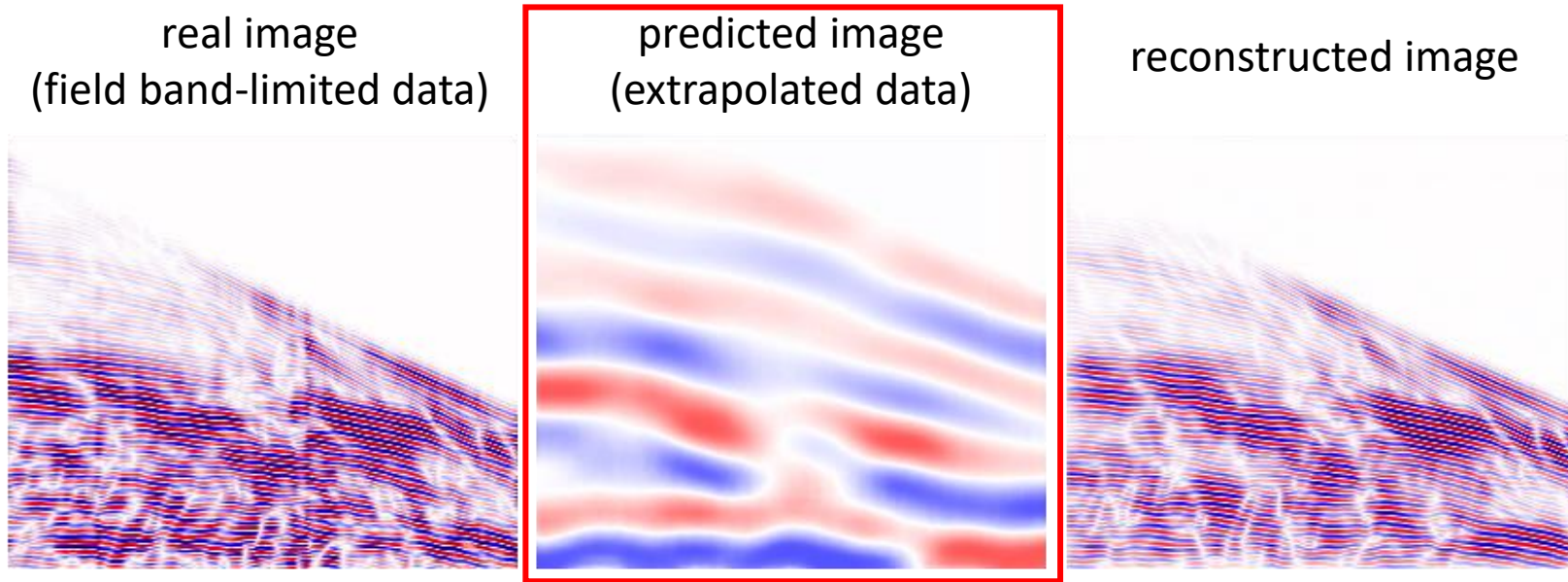


forward
modeling

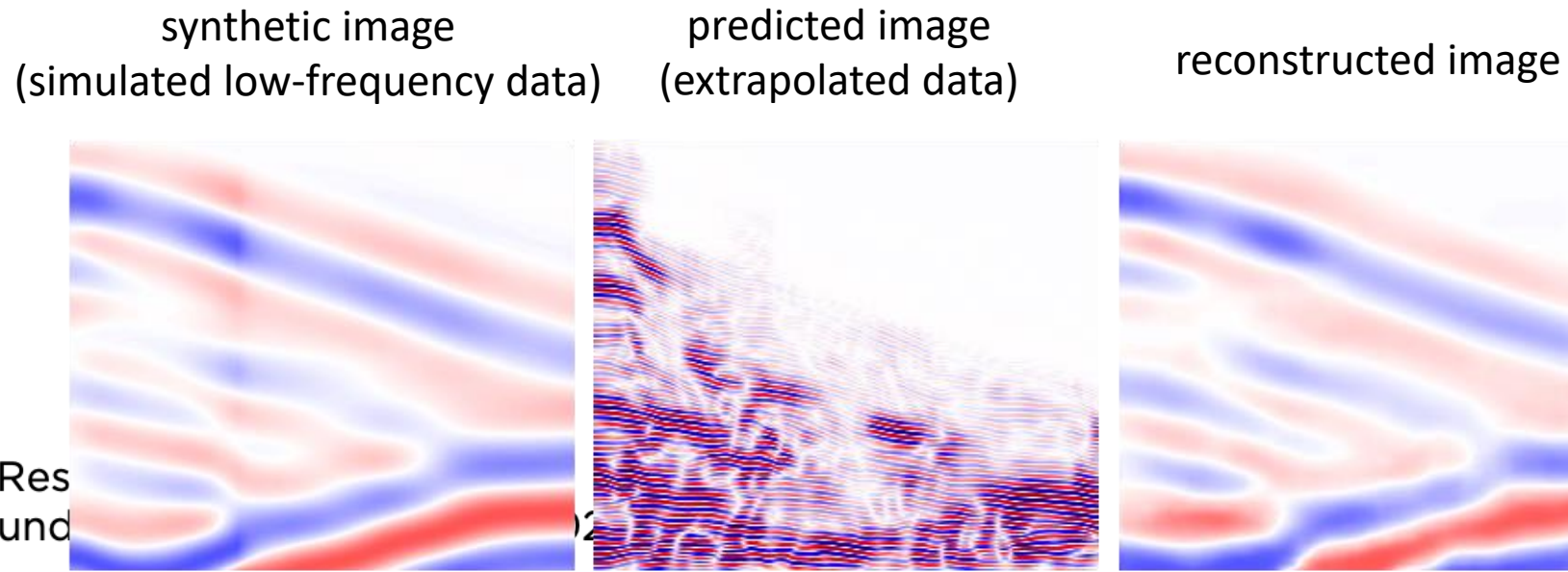


Field-data extrapolation result: from 4-10 Hz to **0-1 Hz**

■ Forward Cycle: Starting from field 4-10 Hz band-limited data



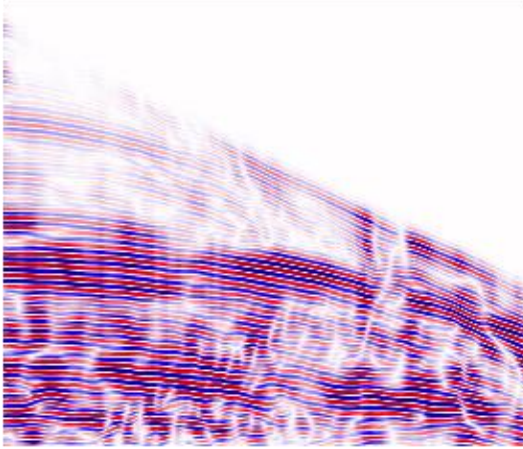
■ Backward Cycle: Starting from synthetic 0-1 Hz low-frequency data



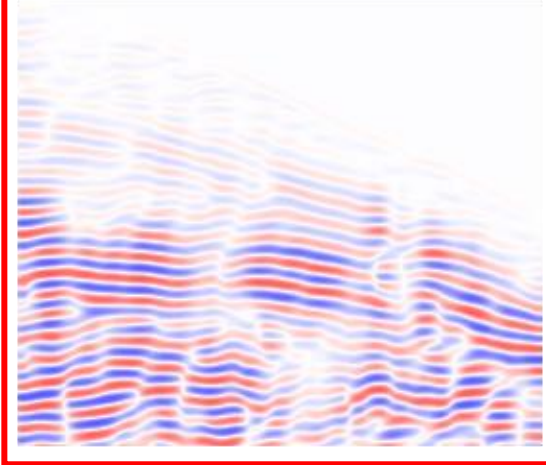
Field-data extrapolation result: from 4-10 Hz to **0-4 Hz**

■ Forward Cycle: Starting from field 4-10 Hz band-limited data

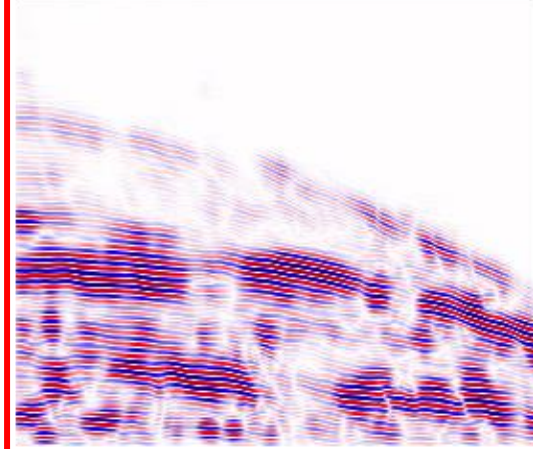
real image
(field band-limited data)



predicted image
(extrapolated data)

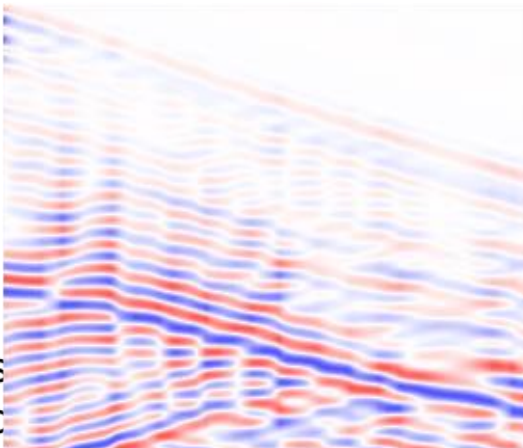


reconstructed image

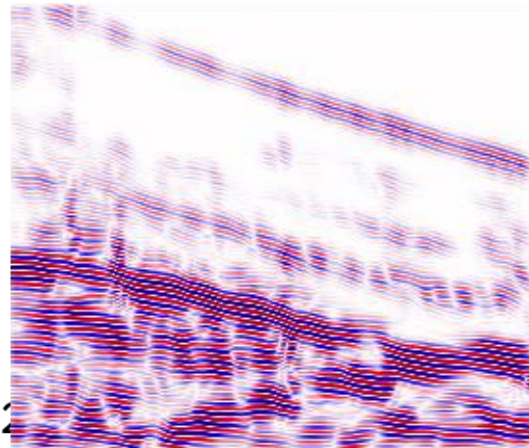


■ Backward Cycle: Starting from synthetic 0-4 Hz low-frequency data

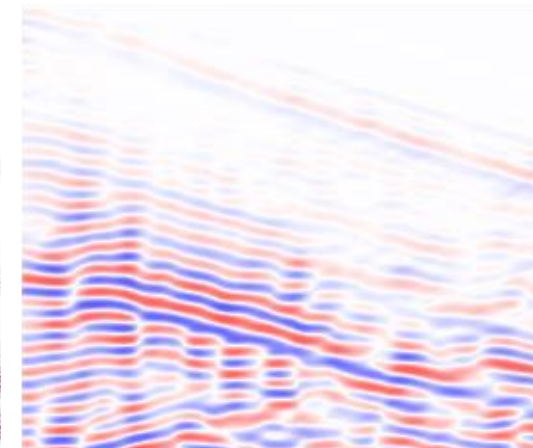
synthetic image
(simulated low-frequency data)



predicted image
(extrapolated data)



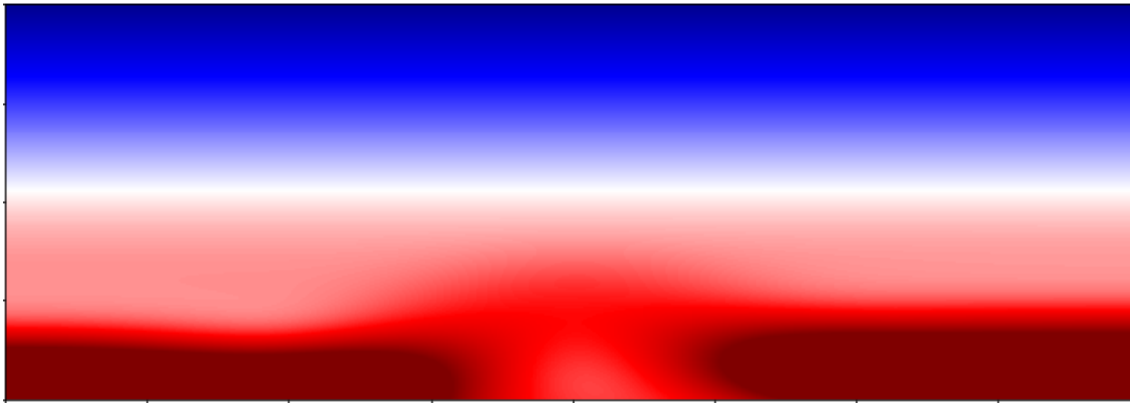
reconstructed image



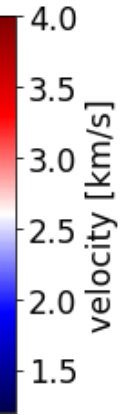
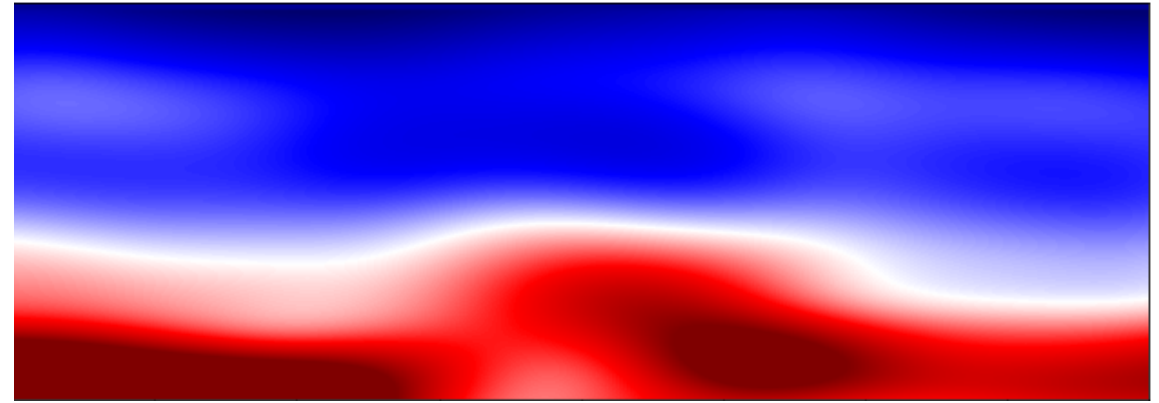
Extrapolated FWI with 3-10 Hz band-limited field data

Cost function: L2 norm of normalized (trace by trace) difference in time domain

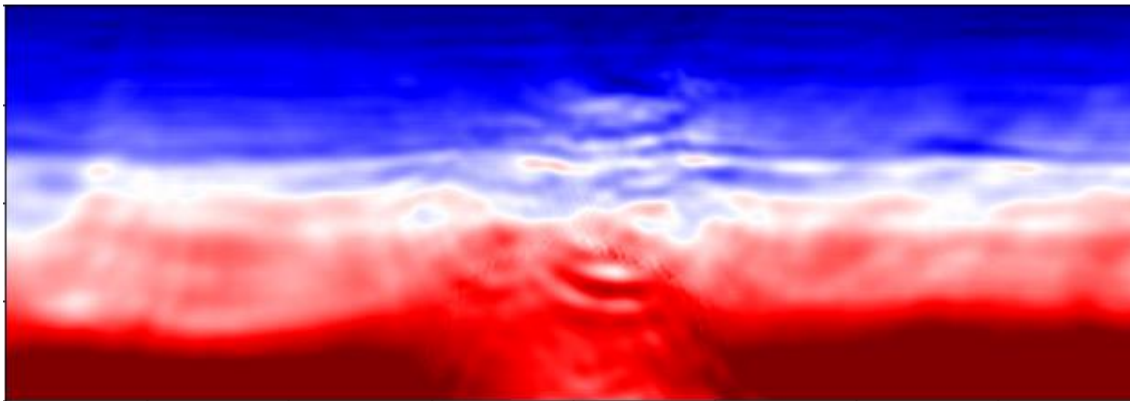
Bad initial model



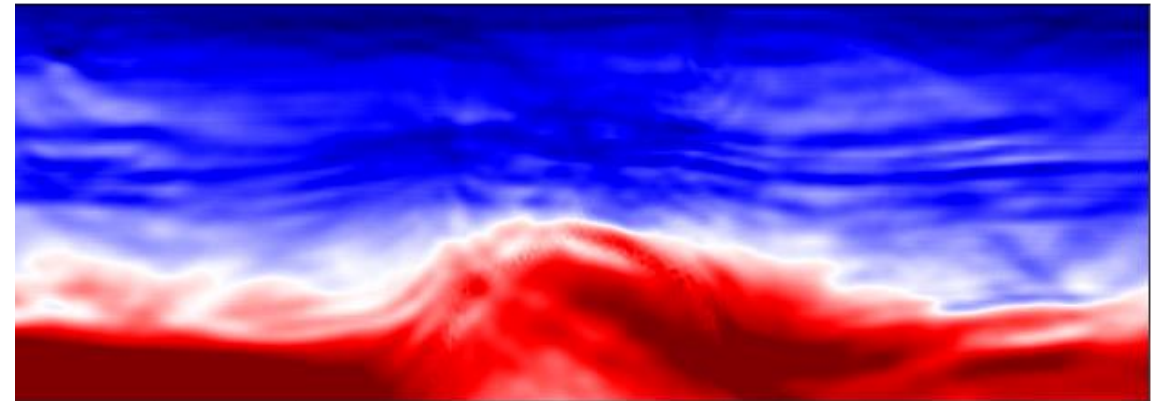
FWI with only extrapolated low-frequency data



FWI started from the bad initial model



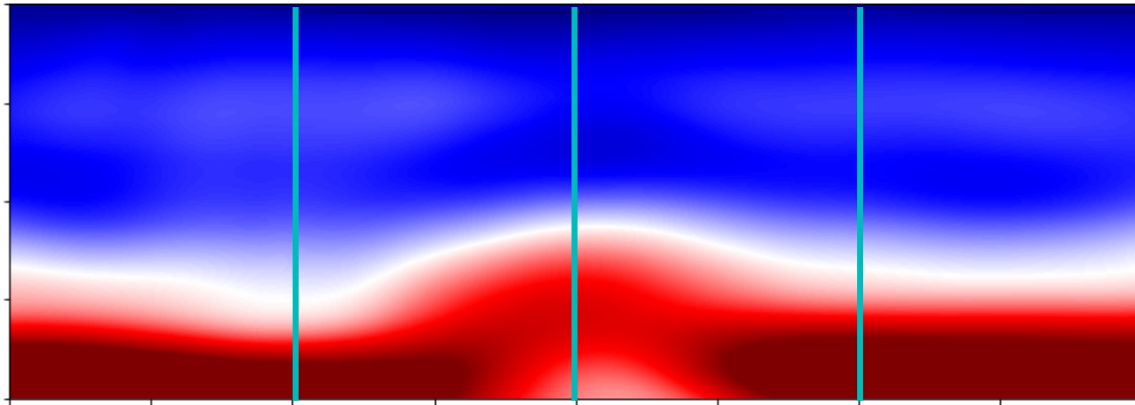
EFWI-CNN started from extrapolated low-frequency data



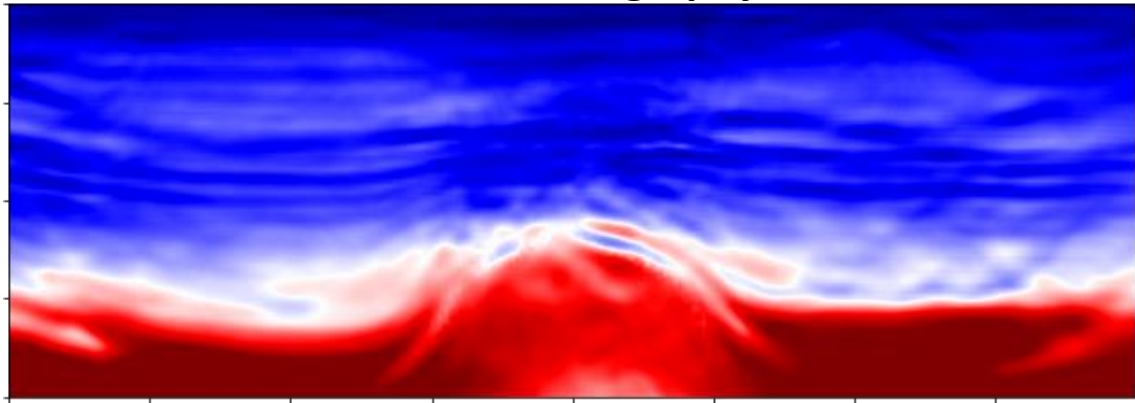
Extrapolated FWI with 3-10 Hz band-limited field data

Cost function: L2 norm of normalized (trace by trace) difference in time domain

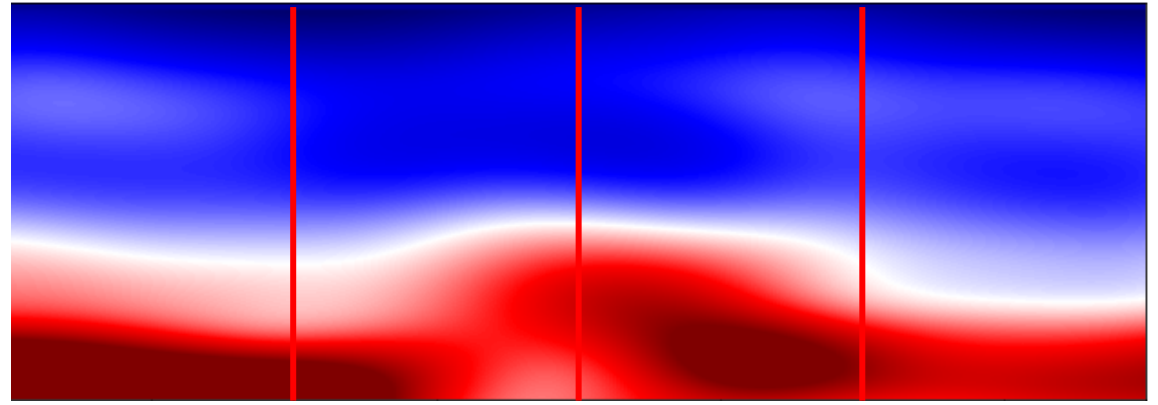
FWI with synthetic data simulated on 'tomography' model



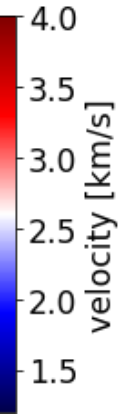
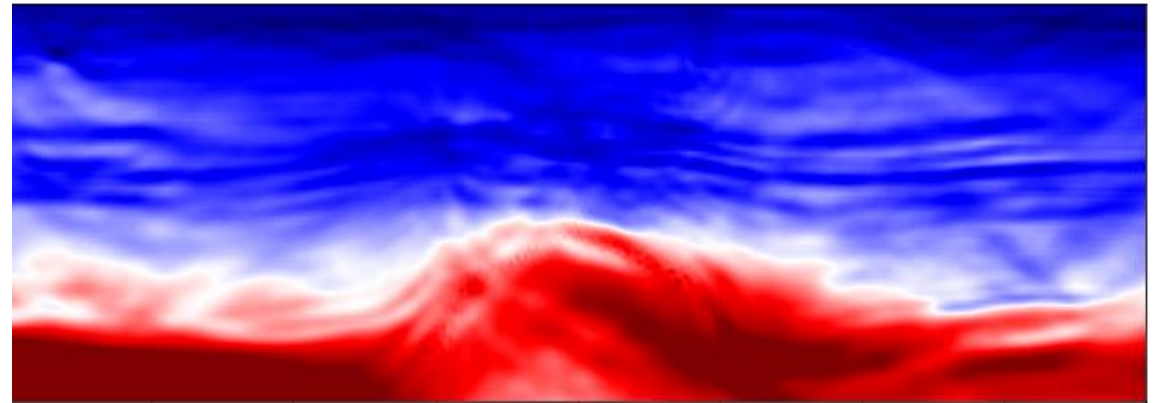
FWI started from synthetic data
simulated on 'tomography' model



FWI with only extrapolated low-frequency data

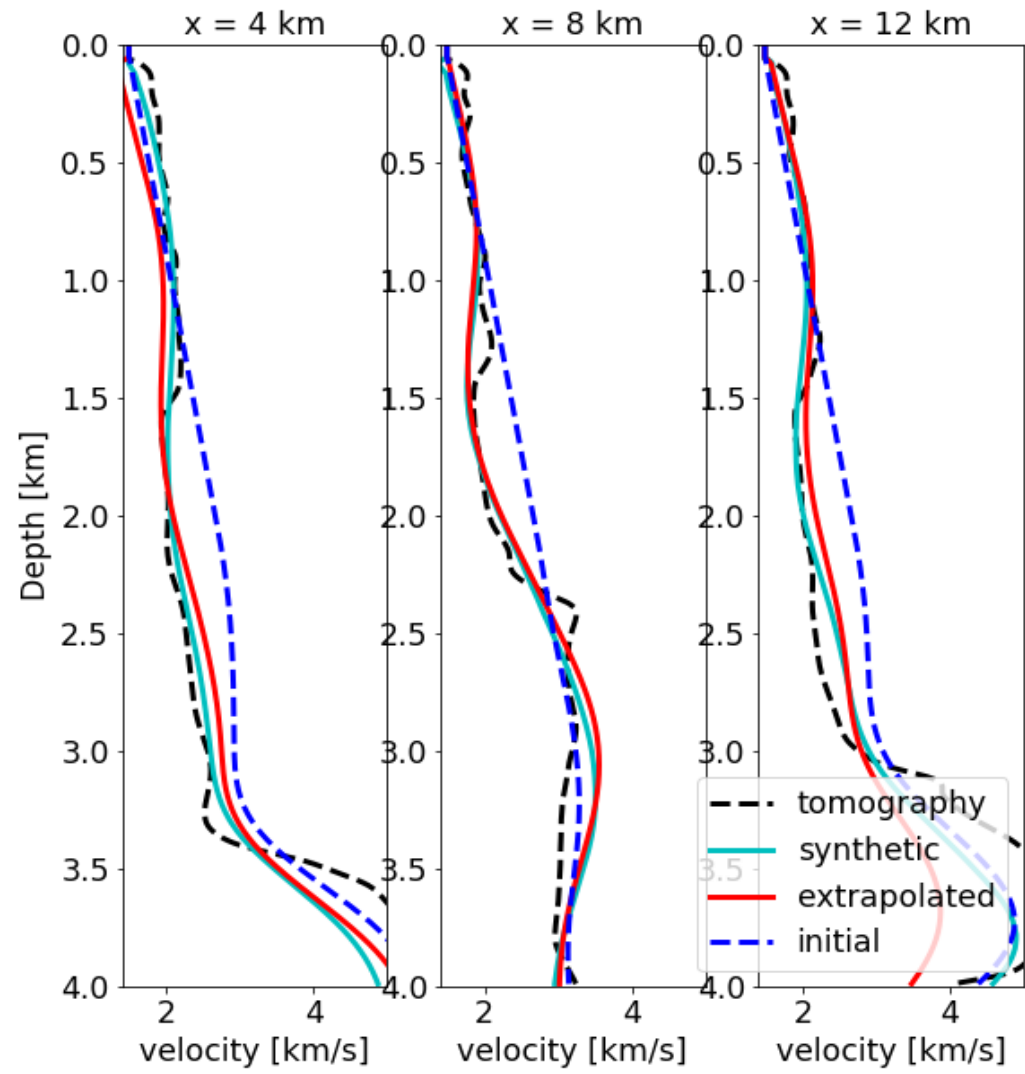


EFWI-CNN started from extrapolated low-frequency data

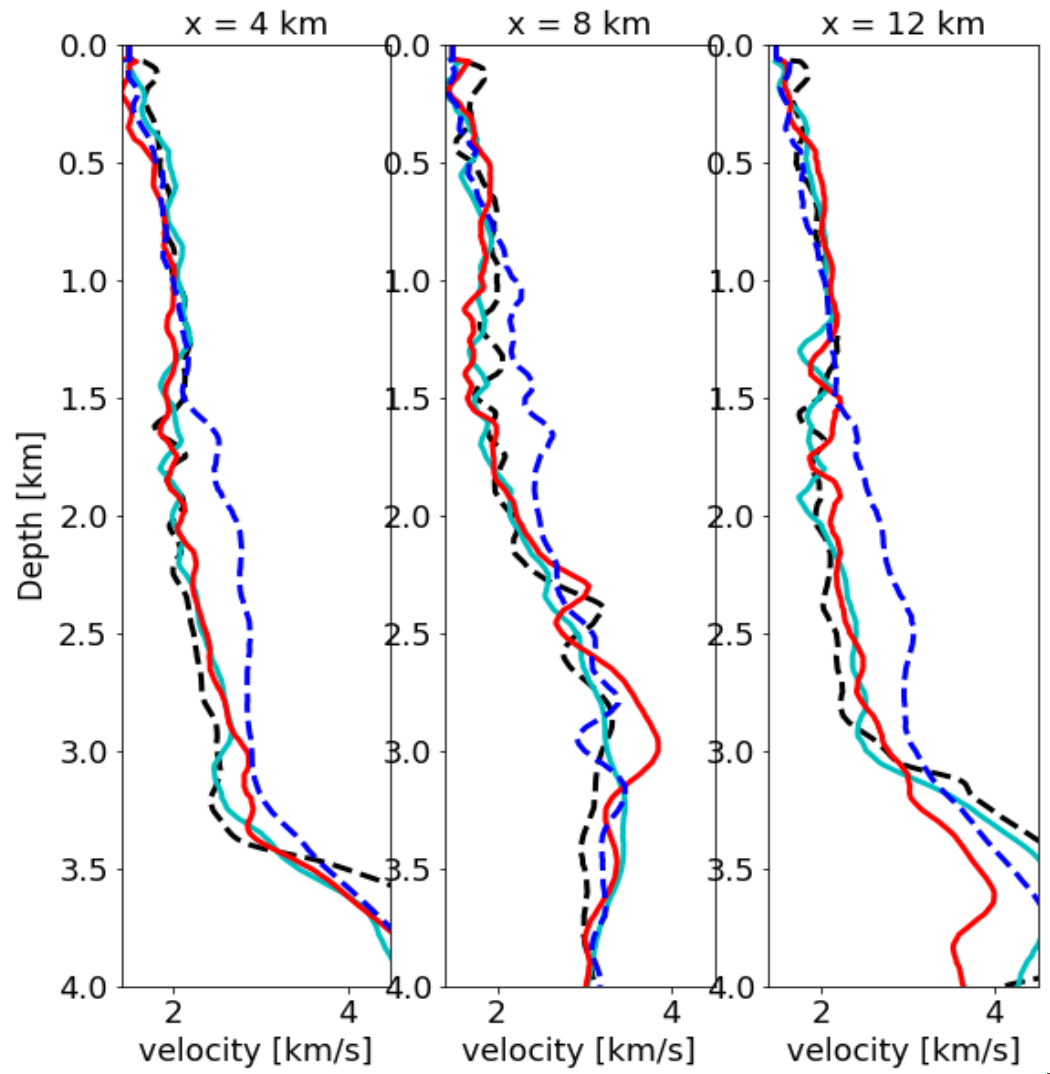


Quality control: Vertical section comparison

starting models



FWI using 3-10 Hz band-limited field data



Summary

- CycleGAN can be trained using unpaired images of field band-limited and synthetic low-frequency shots in the time domain for robust low-frequency extrapolation of the field data.
- Our field-data results validate the benefit of extrapolated low-frequency data for mitigating the cycle-skipping problem of full-waveform inversion.
- The wavelet to synthesize the low-frequency data on the training model should be used for full-waveform inversion using the extrapolated low frequencies.



Limitations and future work

- more robust FWI with the extrapolated data
- QC with RTM and image gathers

■ interpretable AI?

Sun and Demanet, 2022, **Extrapolated surface-wave dispersion inversion:** SEG, Expanded Abstracts, in press.

■ surface waves

Second International Meeting for Applied Geoscience & Energy (IMAGE22)

- Session Style: Oral Presentation
- Session ID: NS 2 (Near Surface)
- Session Title: Advanced Processing and Machine Learning 2
- Presentation Date and Time: August 31, 2022 from 1:45 PM to 2:10 PM



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- Thank you for your attention.

