

Low frequency extrapolation with deep learning

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Motivation: Full waveform inversion (FWI)

Brief introduction to FWI



• Forward modeling

$$\nabla^2 u(\mathbf{x}, \omega) + \frac{\omega^2}{v_p^2(\mathbf{x})} u(\mathbf{x}, \omega) = -s(\mathbf{x}, \omega)$$

• Inversion objective function

$$C(\mathbf{m}) = \left\| \Delta \mathbf{d} \right\|_p = \left\| \mathbf{d}_{cal}(\mathbf{m}) - \mathbf{d}_{obs} \right\|_p$$

• Optimization

 $\Delta \mathbf{m} = -\alpha (diag(\mathbf{H}_a) + \lambda \mathbf{I})^{-1} \nabla C(\mathbf{m})$



true velocity model (unknown)



observed data



initial velocity model





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Problem: Cycle skipping

Cycle skipping in FWI





(b) Observed seismogram

(c) Calculated seismogram: from a 'good' initial model



schematic of cycle-skipping artifacts in full waveform inversion (Virieux and Operato, 2009)



true velocity model



'good' initial velocity model





inversion result with the 'bad' initial velocity model inversion result with the 'good' initial velocity model MIT EARTH RESOURCES LABORATORY ANNUAL FOUNDING MEMBERS MEETING 2018

1500



Distance (km)

'bad' initial velocity model

Depth (km)







schematic of cycle-skipping artifacts in full waveform inversion (Han, 2013)



true velocity model



the 'bad' initial velocity model



inversion result started from 5HZ



inversion result started from 1-Z







Low frequencies: hard to acquire in field acquisition



(Han, 2013)

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Solution: Deep learning

Deep learning

Deep neural networks

- Data-driven method: a list of layers that transform the input data into an output prediction
- The universal approximation theorem (Hornik et al., 1989)



A supervised learning method: two steps

- Training: learning the coefficients of the neural networks with known low frequencies (output) and high frequencies (input)
- Test: feeding high frequencies into the pretrained neural networks and predicting their unknown low frequency data

Deep learning

Convolutional Neural Networks (CNNs)

- Convolution filter: 128 64 128 64 1
- Activation function: PReLU (He et al., 2015)



• Optimizer: Adam (Kingma and Ba, 2014) with a mini-batch of 20 samples



The architecture of CNNs for LF extrapolation

- Training dataset: 81,000 samples
- Test dataset: 9000 samples
- Trainable parameters: 3,290,946

Be careful of overfitting!





The full-size model to synthesize the test data



The nine submodels to synthesize the training data







Comparison of one trace at the horizontal distance:

(a) (b) x = 1.73 km

(c) (d) x = 2.25 km



Output: Predicted (red line) and true (blue dash line) low frequency recording (0.3–5Hz) **Input:** Band-limited (Black line) recording (5–50Hz)

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Conclusion



METHOD

 an architecture of DNNs to extrapolate the low frequencies of band-limited seismic recordings without any preprocessing and post-processing procedures;

IMPACT

solution to cycle-skipping problem in FWI;

LIMITATION

- the lack of generalizability guarantees;
- demanding training time;



Thanks to MIT ERL and Total S A for support. Thanks for your attention.

Acknowledgements