

Deep nets for making sense of ambient noise?

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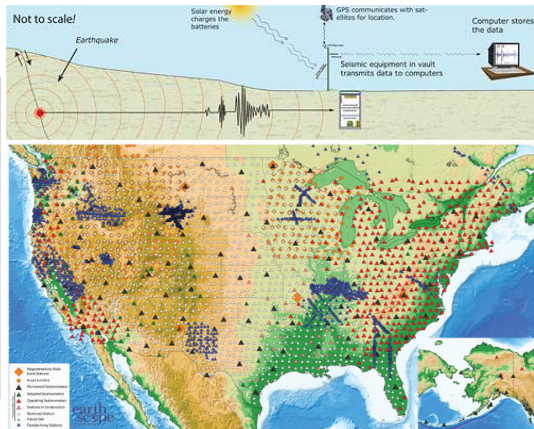
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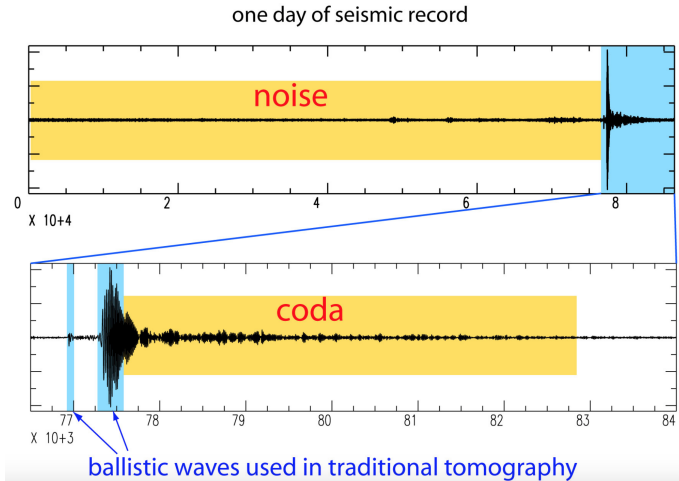
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Example: ambient seismic noise



Credit: EarthScope, usarray.org

Noise, ballistic waves, and coda



What information is present in ambient seismic noise?

Wave equation with random forcing

$$\left(\frac{1}{c^2(x)} (a + \partial_t)^2 - \Delta \right) u(x, t) = n(x, t)$$

Space-time white noise: Gaussian with

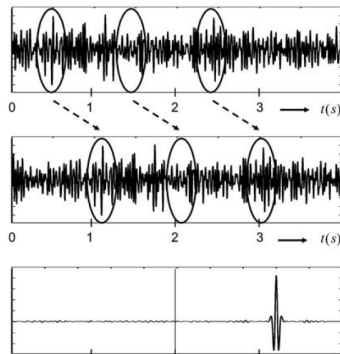
$$\langle n(x, t) n(y, s) \rangle = \delta(t - s) \delta(x - y).$$

- **Pointwise:** $u(x, t)$ has Gaussian statistics in t
- **Pairwise:** $u(x, t)$ and $u(y, s)$ may be strongly correlated
 \Rightarrow may contain info about $c(x)$

Cross-correlations

Cross-correlations are robust to source randomness.
Their peaks indicate traveltimes.

- Time reversal (phys): Fink et al. 1993.
- Time reversal (math) Bal, Papanicolaou, Ryzhik, 2002; Bal, Ryzhik 2003
- CINT imaging: Borcea, Papanicolaou, Tsogka, 2003, 2005
- Seismic interf. (phys): Weaver et al. 2001; Campillo, Paul 2003; Snieder, 2004; Wapenaar et al. 2006
- Seismic interf. (math): Bardos et al. 2008; Colin de Verdiere 2009; Garnier, Papanicolaou, Solna 2009+



Wapenaar et al. 2010

Sample mathematical result (Bardos et al. 2008)

Assume a space-time white noise source. Let

$$C_T(\tau, x, y) = \frac{1}{T} \int_0^T u(x, t) u(y, t + \tau) dt.$$

Then

$$\partial_\tau \langle C_T(\tau, x, y) \rangle = -\frac{e^{-a|\tau|}}{4a} \operatorname{sgn}(\tau) G(|\tau|, x, y)$$

where

$$\left(\frac{1}{c^2(x)} \partial_t^2 - \Delta \right) G(t, x, y) = \delta(t) \delta(x - y).$$

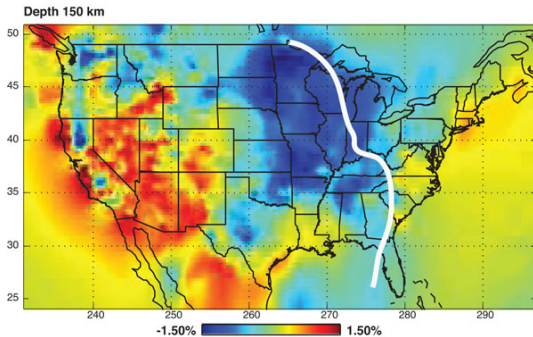
(Extensions: ergodicity, or large T limit, in the high freq regime.)

Seismic interferometry

In turn,

- $G(t, x, y)$ is singular near $t = \text{traveltime}(x, y)$
- $\text{traveltime}(x, y)$ is related to $c(x)$

Hence: determine $c(x)$ by traveltime tomography



Credit: EarthScope, usarray.org

Open questions

Are c.c always the right idea?

What if the source distribution is **not isotropic**?

Is there physics that the lag of a cross-correlation peak **doesn't see**?

Can we **avoid traveltime tomography** to get $c(x)$?

What to do with combinations of **3 or more sensors**?

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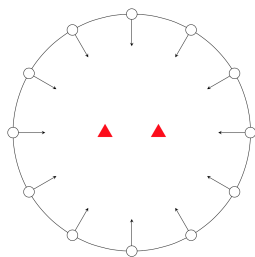
Deep nets provide “cheap” answers to most such questions
(no guarantees, no physics)

Experimental setups

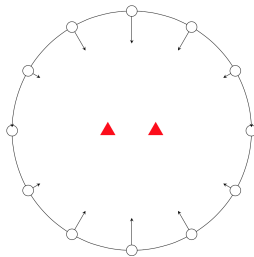
- ① Traveltime inversion with anisotropic sources, homogeneous media
- ② Identification of source distributions
- ③ Inhomogeneous wavespeed inversion

Training: For homogeneous media, generate new data on the fly, seen once and never again. For inhomogeneous media, direct solve with conventional SGD + data augmentation

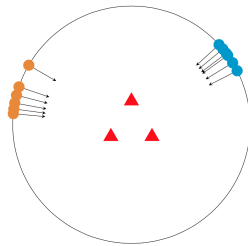
Traveltime inversion



Isotropic

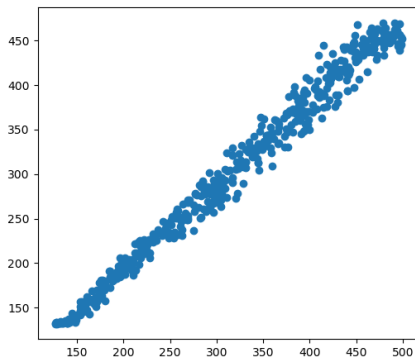


Directional ($\sin^2 \theta$)

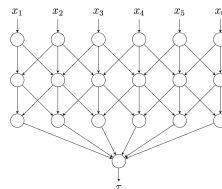


Directional (wedges)

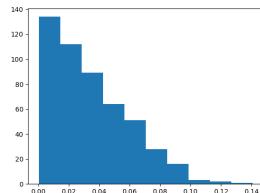
Traveltime inversion: 2 sensors suffice



Estimated vs true traveltime (test samples)

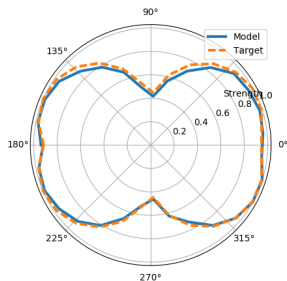
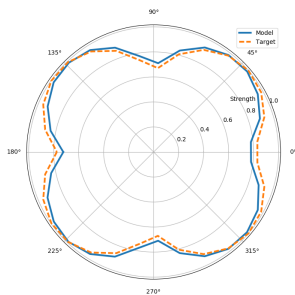


Locally connected
(also works with CLSTM)



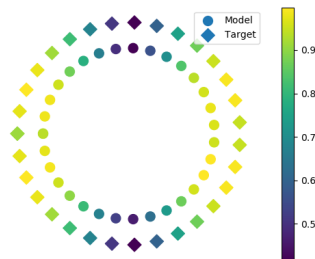
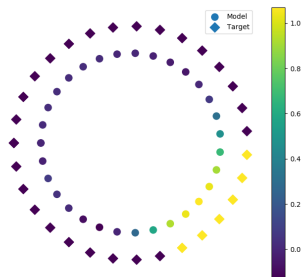
Distribution of relative errors

Inversion of source directionality



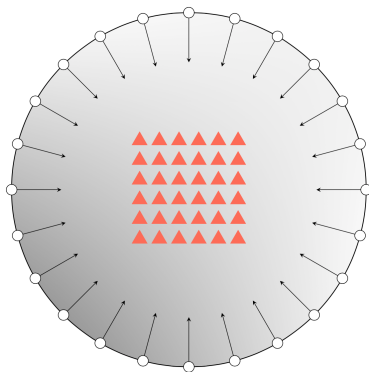
Estimated vs true source strength of the form $a \sin \theta + b \cos \theta$ (test samples). Need CLSTM architecture.

More Source Directionality

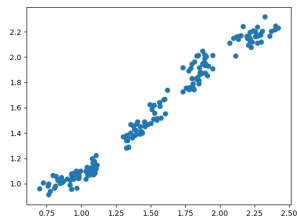


Left: network trained in a wedge distribution (with three sensors).
Right: same as previous slide.

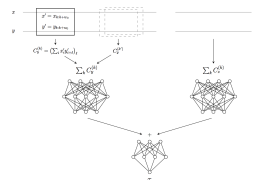
Inversion of heterogeneous wavespeeds



$$c(x) = ax_1 + bx_2 + c$$

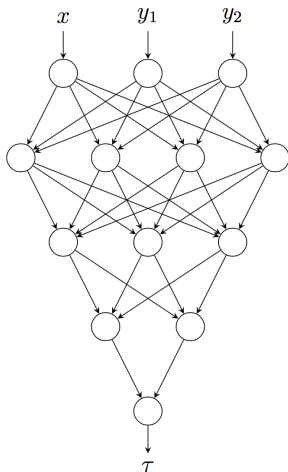


Estimated vs true traveltimes

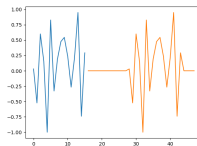


Relational network

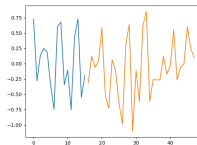
What are the nodes actually computing? (1)



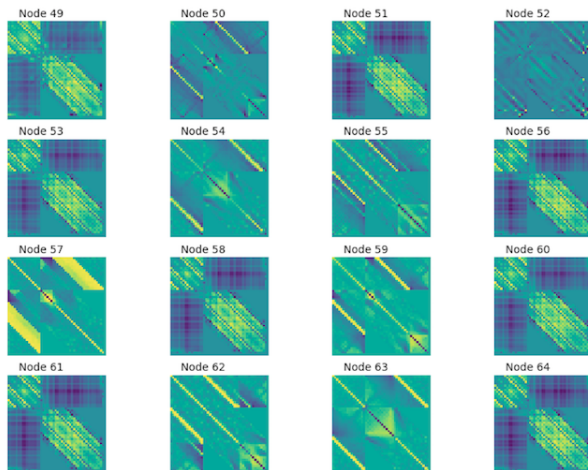
Noiseless:



Noisy:

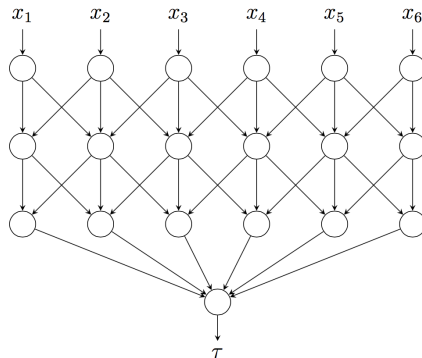


What are the nodes actually computing? (2)

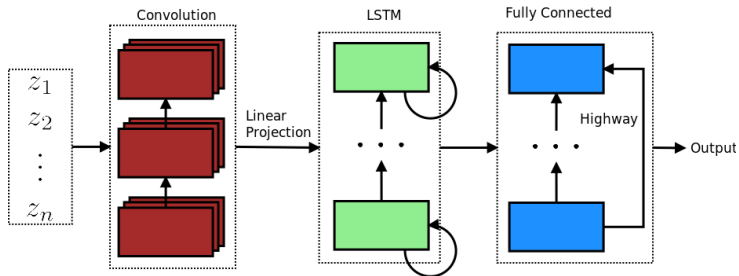


Regress quadratic monomial on hidden nodes.

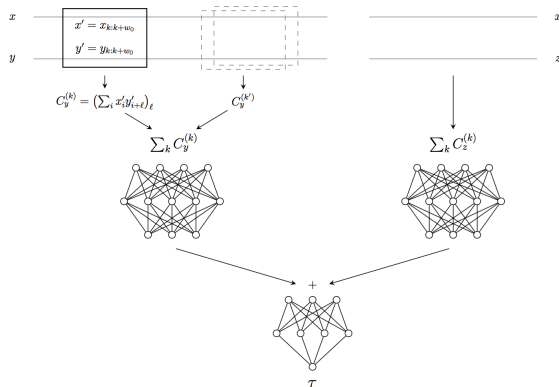
Architectures: Locally connected



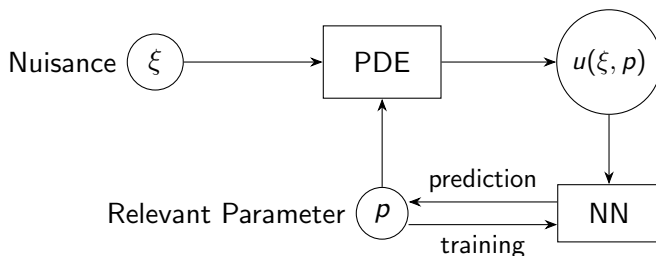
Architectures: CLSTM



Architectures: Relational



Automatic De-parameterization



- ξ : random source
- p : local wave speed, source distribution, etc
- $u(\xi, p)$: passive seismic data

Goal: create representations of the data $u(\xi, p)$ that are mostly *invariant* to ξ and have enough information to recover p . In limited situations, this is what cross-correlations does.

Conclusions

- *Blessing:*
Data-centric predictions **without a forward or inverse physical model** (automatic de-parametrization of forward simulations that involve nuisance parameters that cannot be estimated during the inversion)
- *Curse:*
Physical content is (at best) **buried in the network**
- *Curse:*
Lack of performance guarantees
(possible overfitting, testing out of sample)

Outlook: characterization of scatterers, better performance in the inhomogeneous case

References I

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