Modeling nucleation and propagation of shear rupture on rough faults with a large range in wavelengths

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Fault roughness- self-affine fractals

Spectral density

 $P(k) = Ck^{-(2H+1)}$

H - Hurst exponent

$$C = 1x10^{-6} - 2x10^{-4}$$



Study numerically the effect of roughness on the nucleation and

propagation of shear rupture







Friction laws





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Rate and state friction (Dieterich, 1979)- μ (V $_{rel}, \theta$)

$$\mu = \mu^* + aln\left(\frac{v_{\rm rel}}{v^*}\right) + bln\left(\frac{v^*\theta}{d_c}\right)$$

 V_{rel} - slip velocity, V*- reference velocity μ *- steady-state friction at V = V* a and b- material dependent empirical constants d_c - critical slip distance, θ - state variable:

Aging law

$$\dot{\theta} = 1 - rac{\theta v_{
m rel}}{d_c}$$





Conceptual approach





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Numerical challenges and approach

- Larger fault with fixed minimum wavelength => larger range in wavelengths
- 1. Computationally expensive
 - => Hanging nodes
- 2. The assumption of small slip relative to the size of the elements may not be valid
 - => Mortar Finite Element Method

Continuity in an integral sense

Implementing slip weakening and rate and state friction laws









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Mortar Finite Element



1. Finite element discretization

Virtual work:
$$\delta \Pi(\mathbf{u}, \delta \mathbf{u}) = \delta \Pi_{\text{int,ext}}(\mathbf{u}, \delta \mathbf{u}) + \delta \Pi_{\text{c}}(\mathbf{u}, \delta \mathbf{u})$$

Total Lagrangian formulation Lagrange multipliers (λ)
(Bathe, 1996) $\delta \Pi_{\text{c}} = \int_{\gamma_{c}^{(1)}} \lambda \cdot (\delta \mathbf{u}^{(1)} - \delta \mathbf{u}^{(2)}) d\gamma$



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- 2. Contacts are updated each time step
- 3. Contact constraints

r

r

Normal direction: non-penetration condition

$$\int_{\gamma_c^{(1)}} \delta \lambda_n g_n d\gamma \ge 0, \qquad \lambda_n \ge 0, \qquad \lambda_n g_n = 0$$

Tangential direction: Coulomb's law

$$\int_{\gamma_c^{(1)}} \delta \lambda_t (v_{t,rel} - \beta \lambda_t) d\gamma = 0,$$

 $\psi \coloneqq |\lambda_t| - \mu |\lambda_n| \le 0, \qquad \beta \ge 0, \qquad \psi \beta = 0$

 g_n - gap function, $v_{t,rel}$ - relative velocity,

 μ – friction coefficient





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- 4. Variable time step
- Quasi-static stages: backward Euler
- Dynamic stages: implicit Newmark
- 5. A primal-dual active set strategy
- Dividing slave nodes into non-active, stick, and slip node sets
- Replacing the inequality contact constraints by complementarity functions (Hueber and Wohlmuth, 2005)
- Consistent linearization to give iterative semi-smooth Newton scheme
- Static condensation of the Lagrange multipliers (Wohlmuth, 2000)





Quasi-static benchmark for rate and state



Example: Finite fault in a continuous domain



Smooth fault



Rough fault: $b_r = 0.001$



The effect of roughness amplitude



 By implementing friction laws into the Mortar Finite Element method, we model the nucleation and propagation of shear rupture along rough faults with a large range in wavelengths.

 We numerically observe and quantify the significant effect of roughness on the following quantities: (1) Seismic moment; (2) Stress drop; (3) Slip rate; and (4) Nucleation and propagation properties such as nucleation length, rupture velocity, and breakdown zone.





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Thank You!