

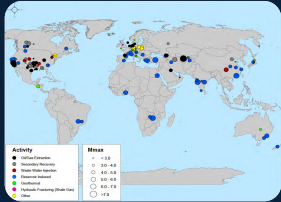
Deep learning applied to induced seismicity – Earthquake detection, location and forecasting

Chen Gu

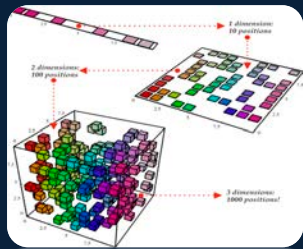
POSTDOCTORAL ASSOCIATE [EARTH, ATMOSPHERIC AND PLANETARY SCIENCES]

In collaboration with M. Nafi Toksöz, Youssef M. Marzouk, Saied Mighani, and J. Brian Evans

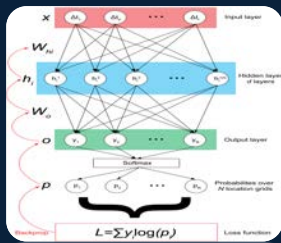
Overview



- Induced Seismicity Increases: Observations and Complexities

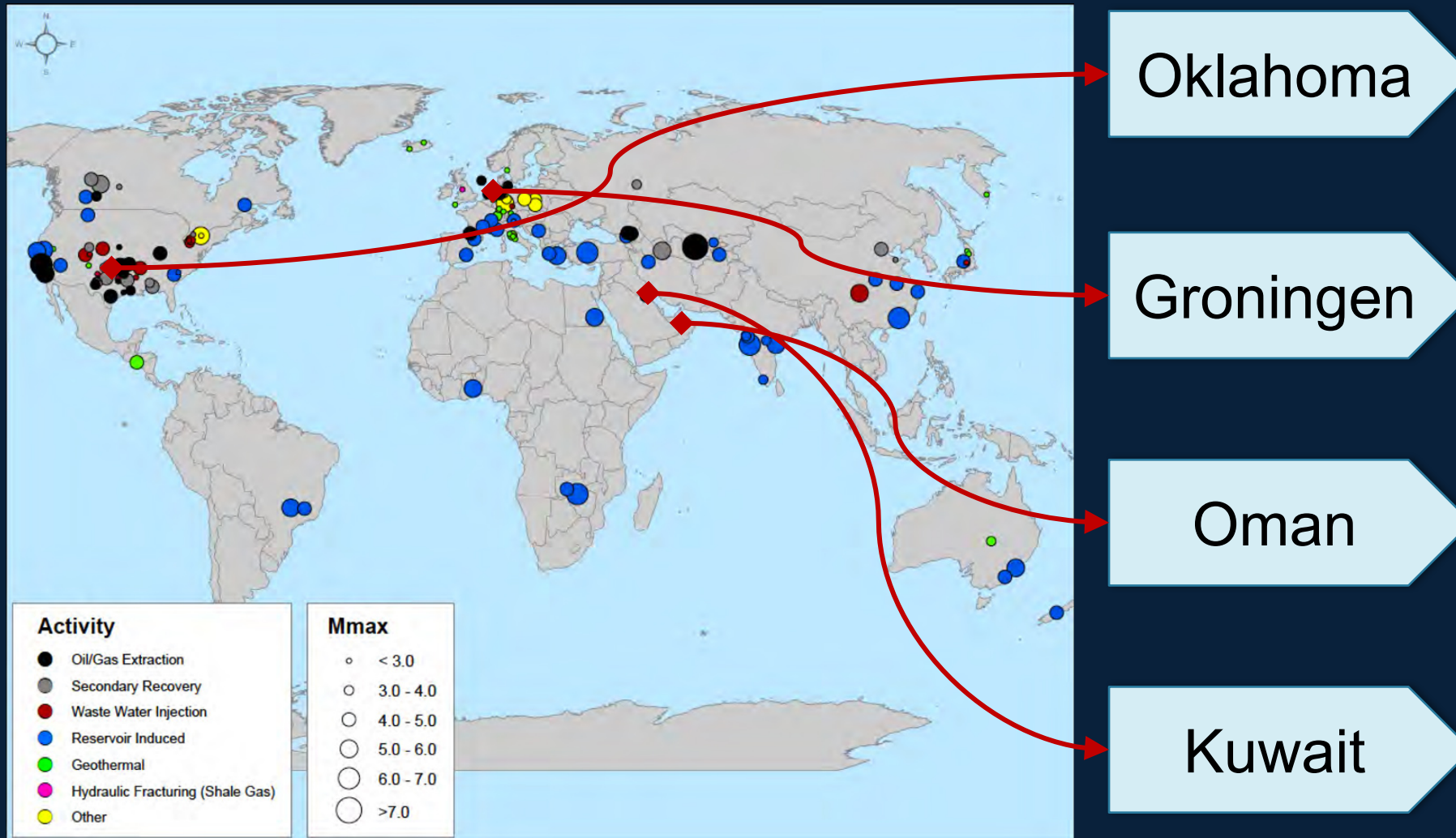


- Seismic Data Interpretation and Prediction: Uncertainty and Efficiency Challenge



- Deep Learning Applications: Detection, Location and Forecasting

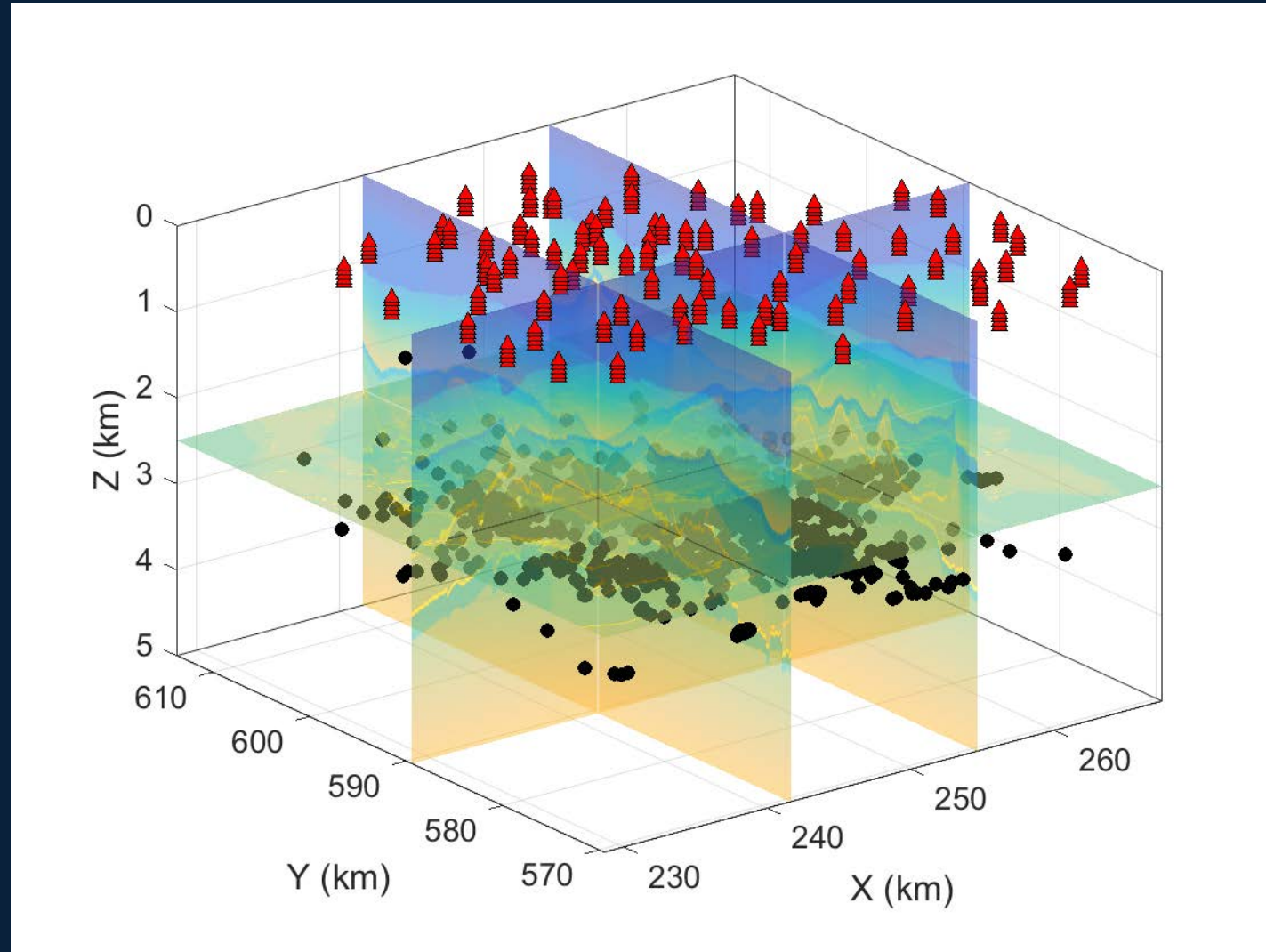
Induced Seismicity in the World



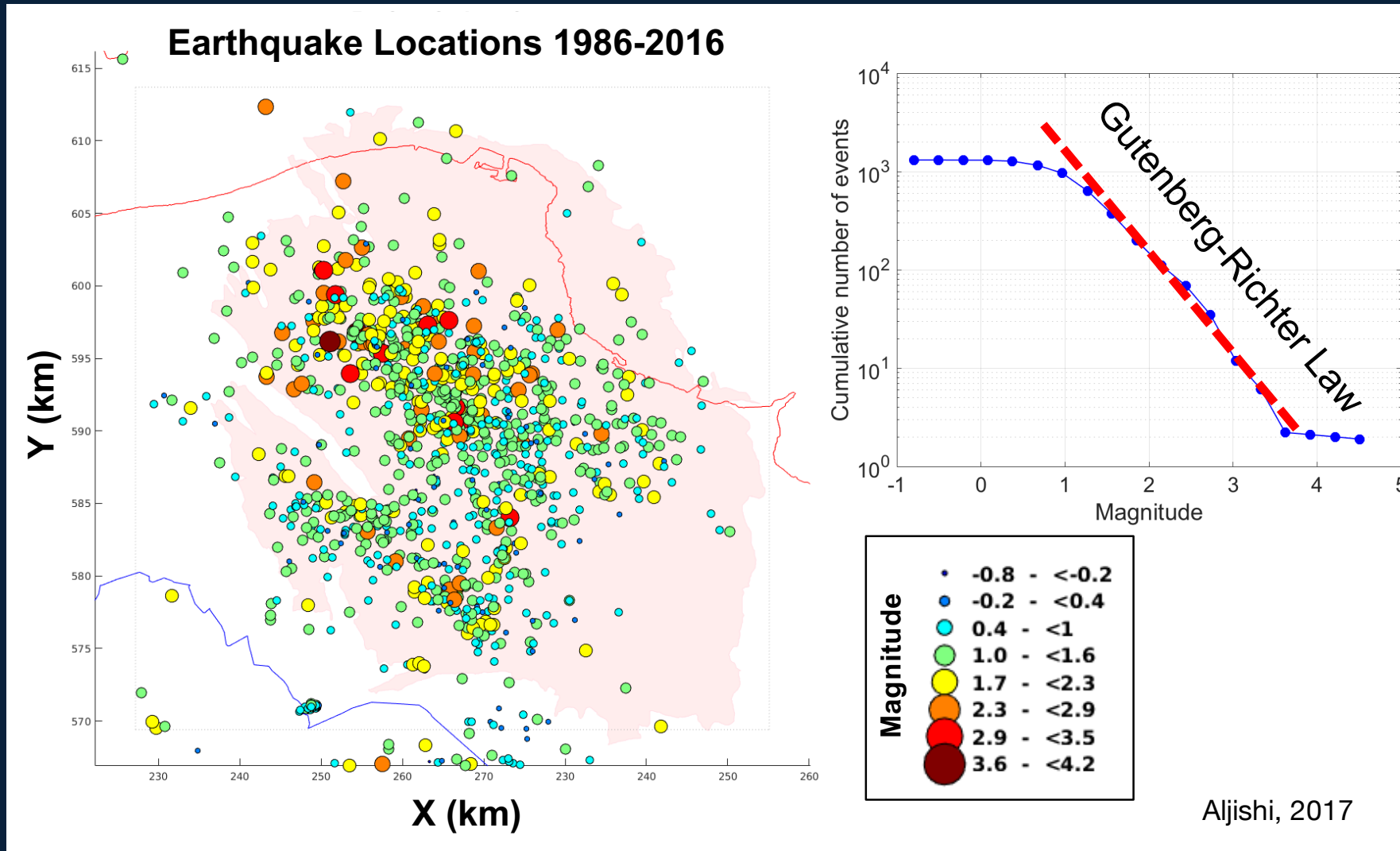
<http://www.nofrackingway.us/2013/12/25/frackquakes-seismic-guidelines-for-frackland-buildings/>

Induced Seismicity in Groningen

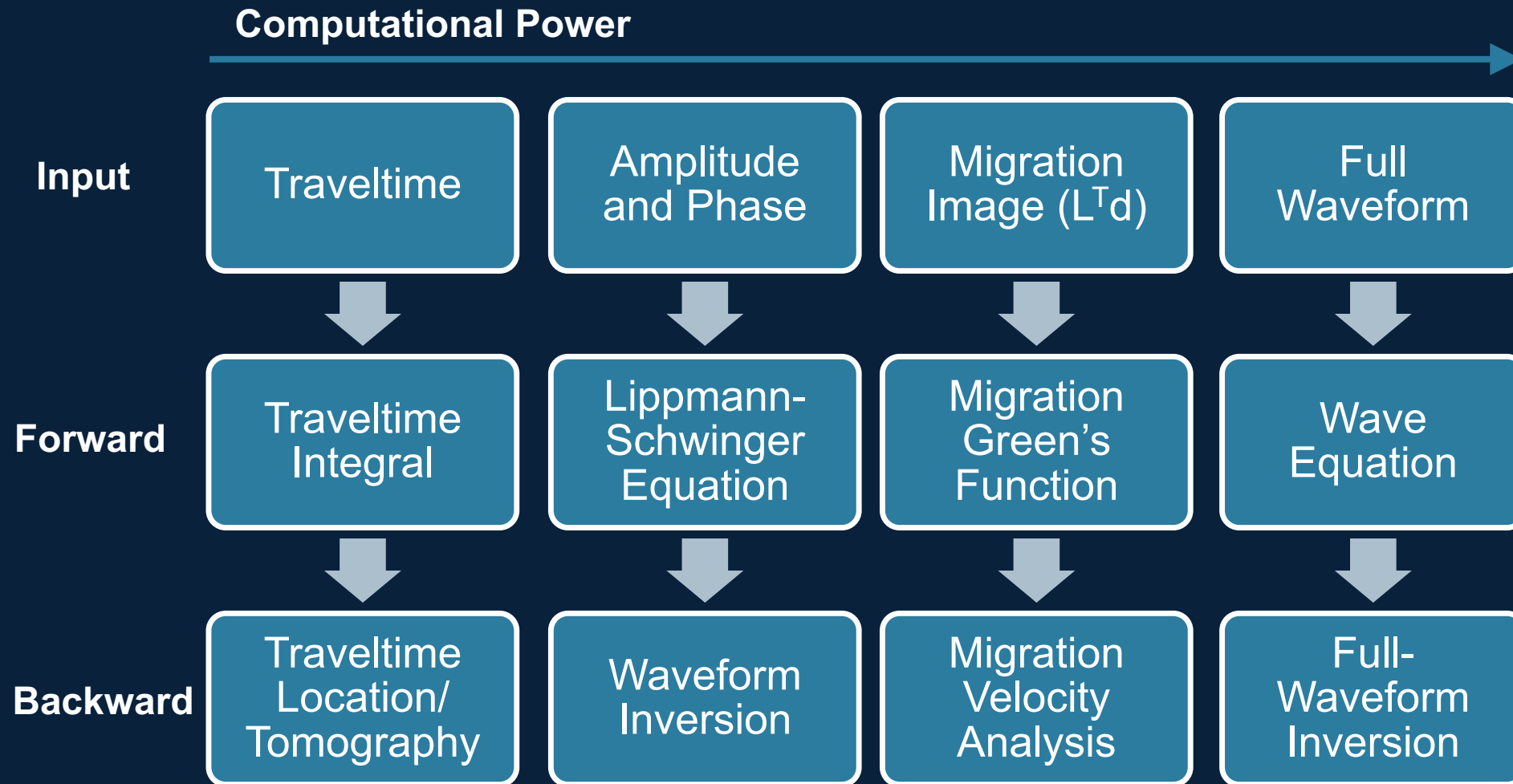
- 68 boreholes
- 1478 located events since 1986



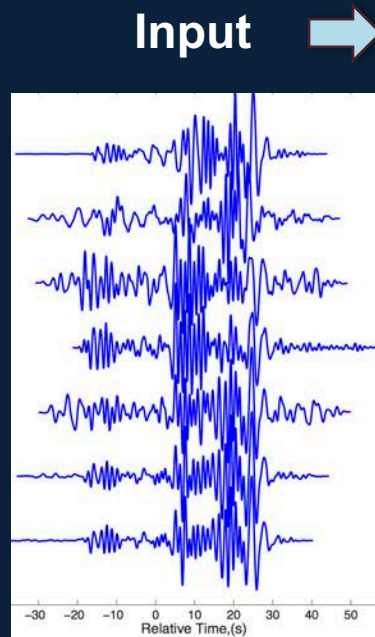
Induced Seismicity in Groningen



Overview of Classical Seismic Inversion



An Example of Bayesian Inference



Simplest Bayesian Formulation



Location Sampling



Velocity Model Sampling



$$\begin{bmatrix} M_{11} \\ M_{22} \\ M_{33} \\ M_{12} \\ M_{23} \\ M_{13} \end{bmatrix}$$



$$\begin{bmatrix} X \\ Y \\ Z \end{bmatrix}$$



$$V$$

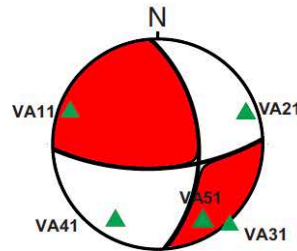
Output

Gu et al, *GJI*, 2018

Bayesian Machine – Mode III



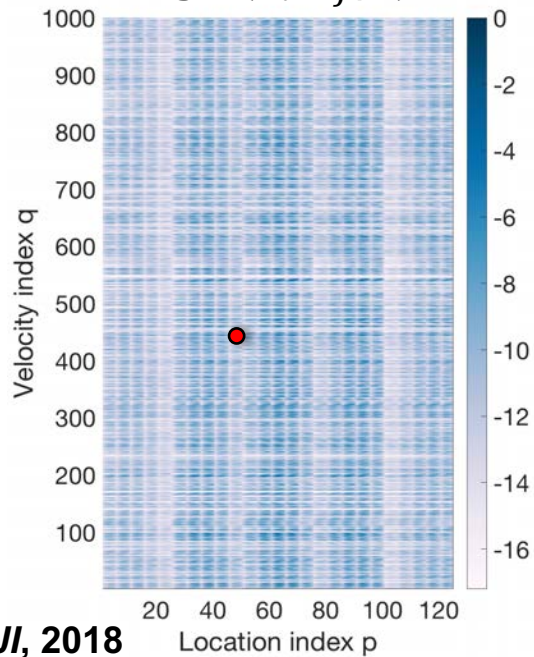
Simplest Bayesian Formulation



$$P(m|x^*, V^*, d)$$



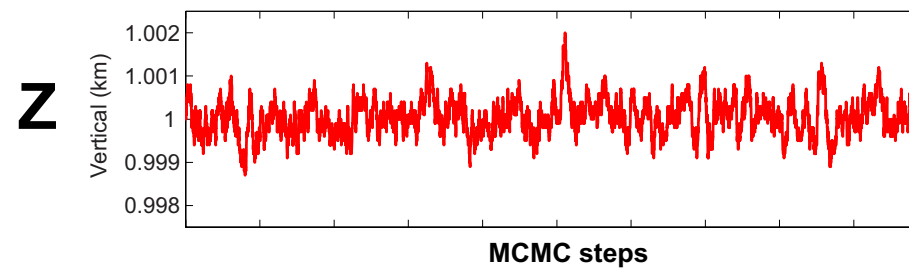
$$\log P(x_i, V_j | d)$$



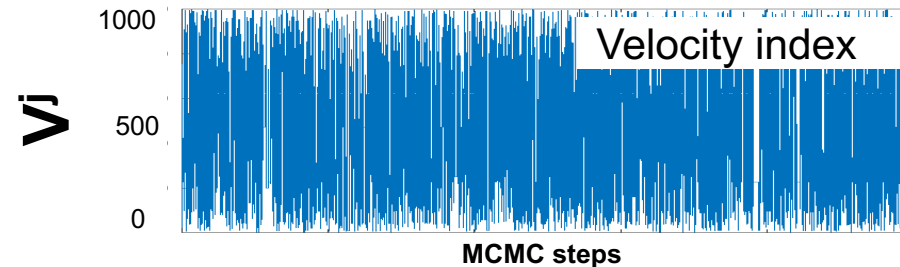
Gu et al, *GJI*, 2018

Location index p

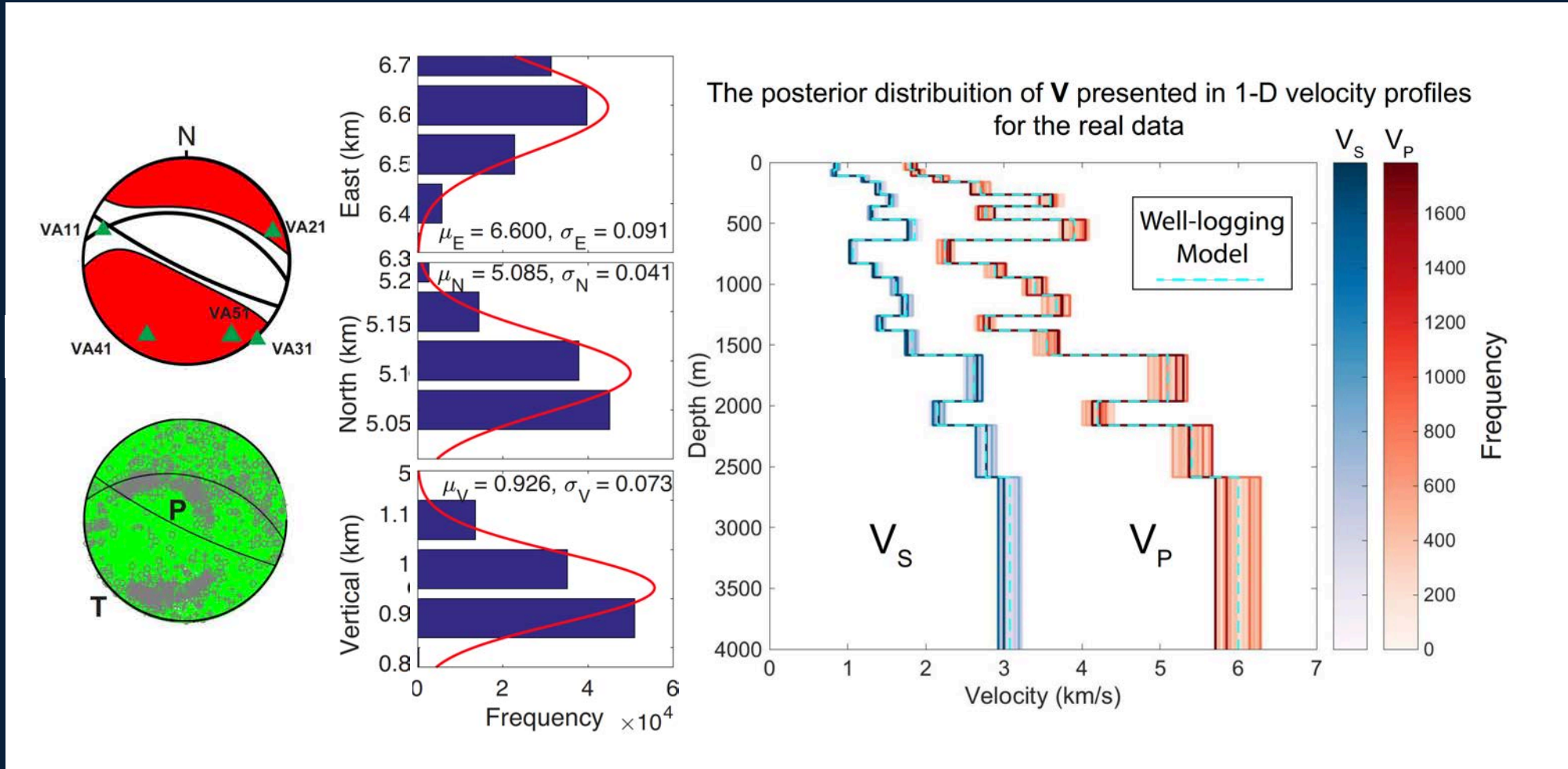
Location Sampling



Velocity Model Sampling

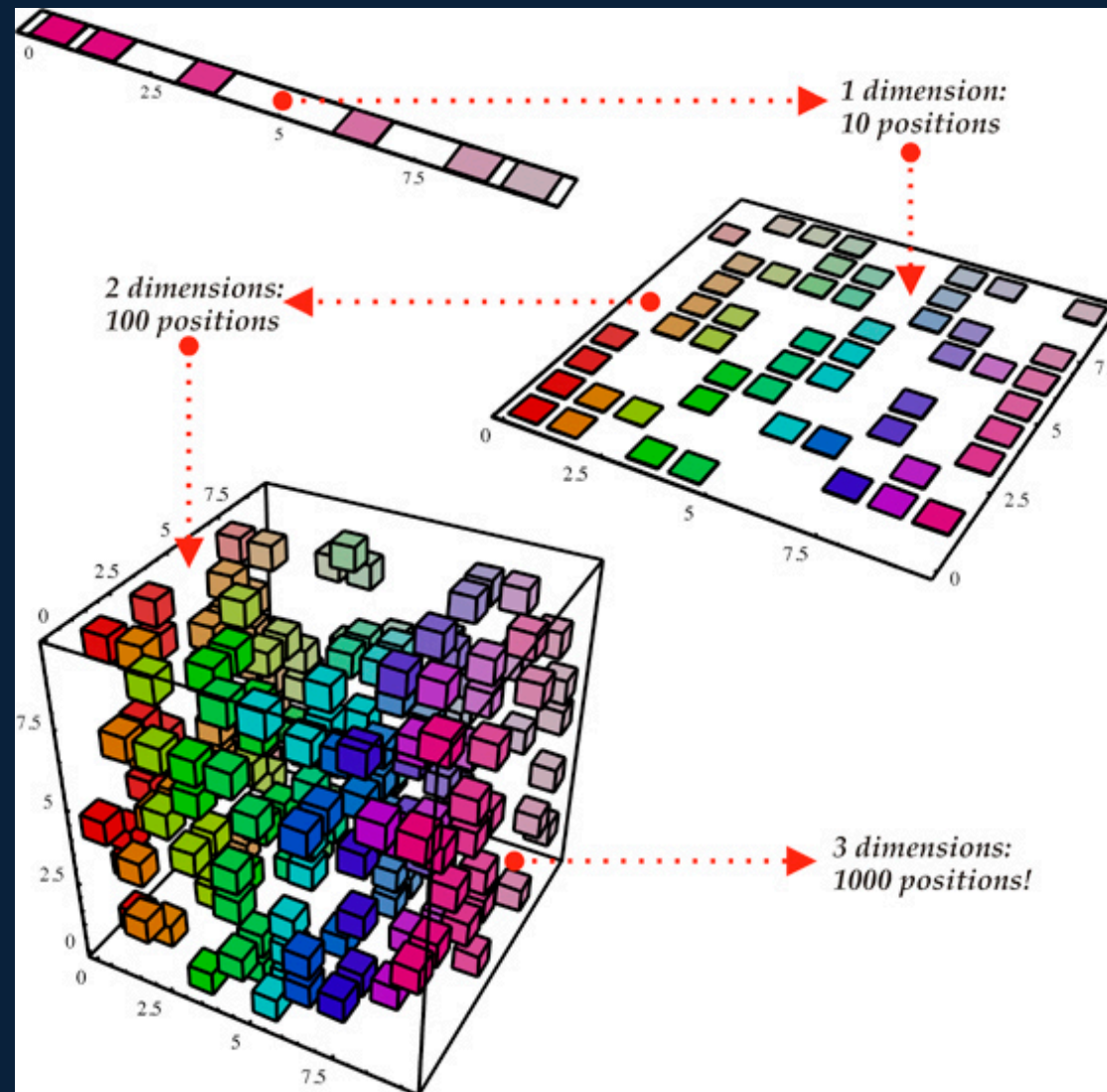


Bayesian Machine Output



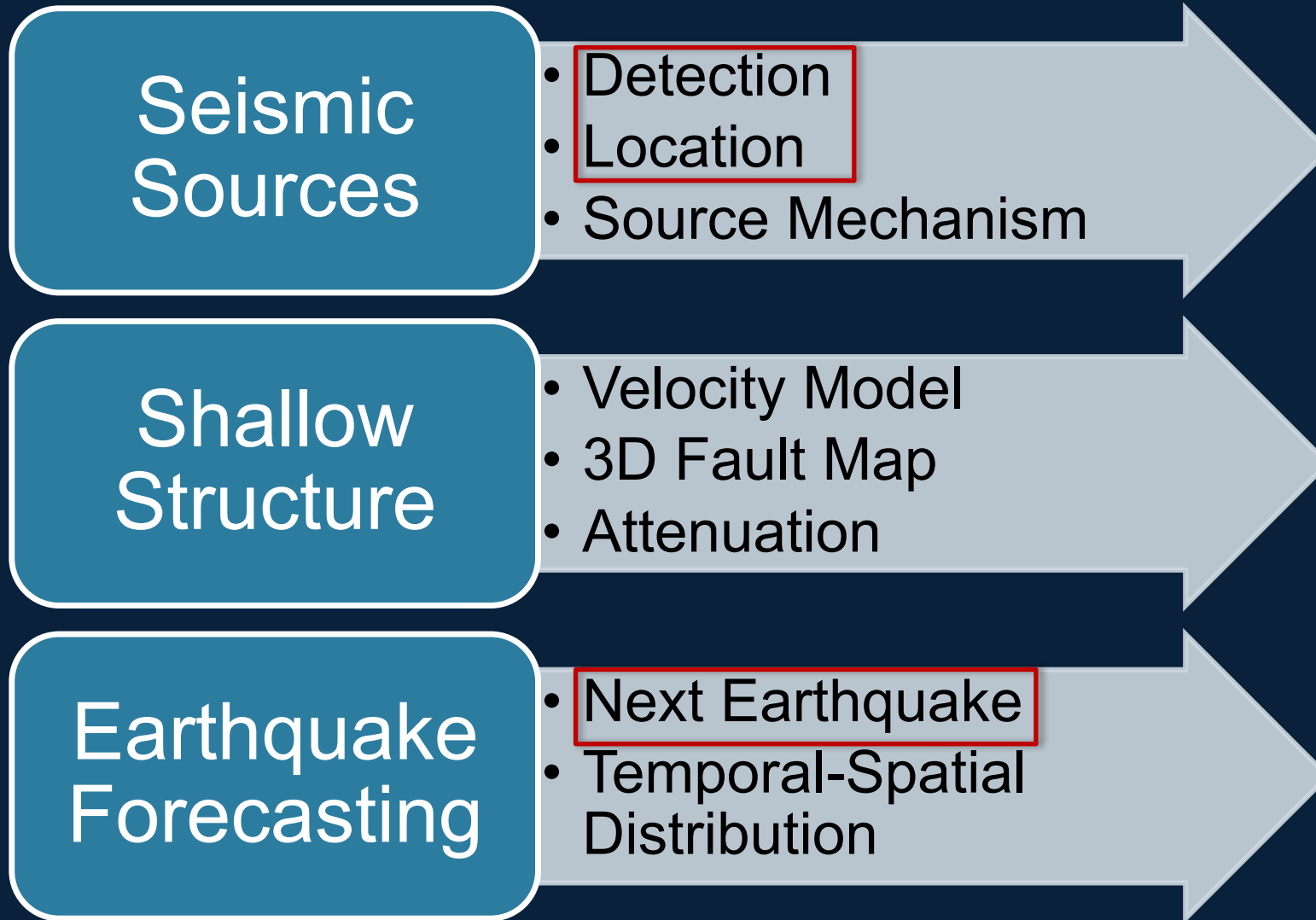
Gu et al, *GJI*, 2018

Curse of Dimensionality

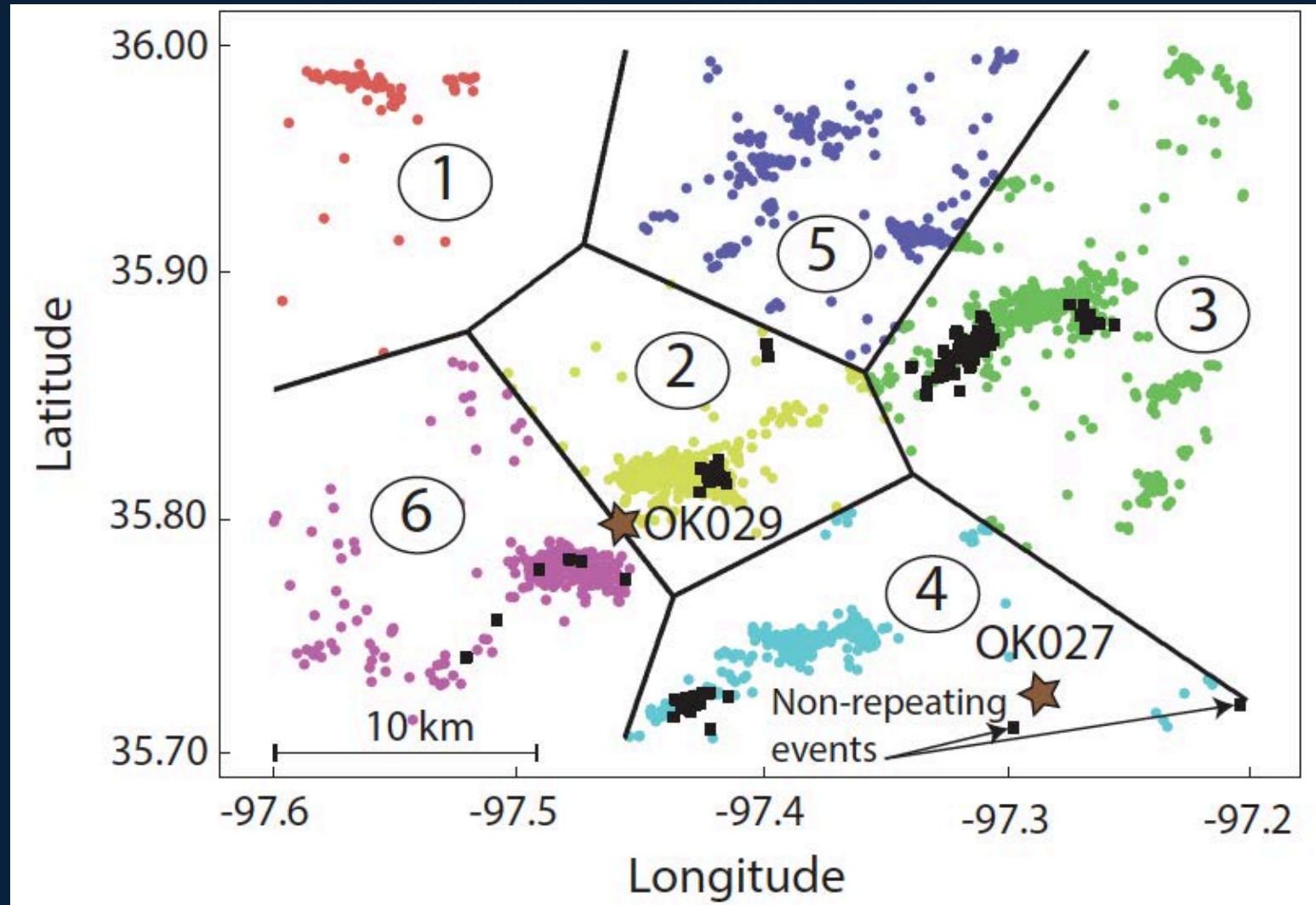


<https://haifengl.wordpress.com/2016/02/29/there-is-no-big-data-in-machine-learning/>

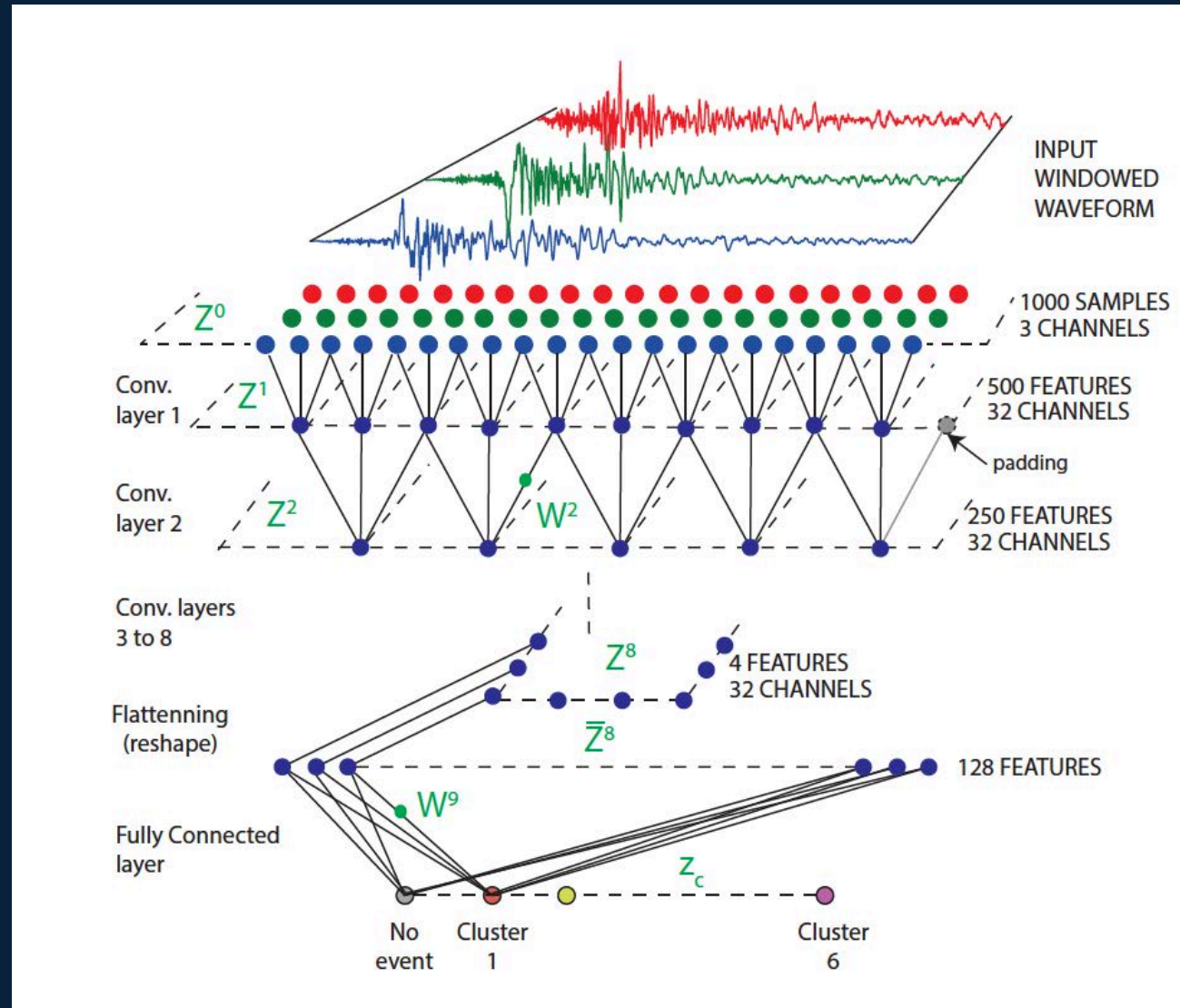
Deep Learning Possibilities



Deep Learning Detection and Location

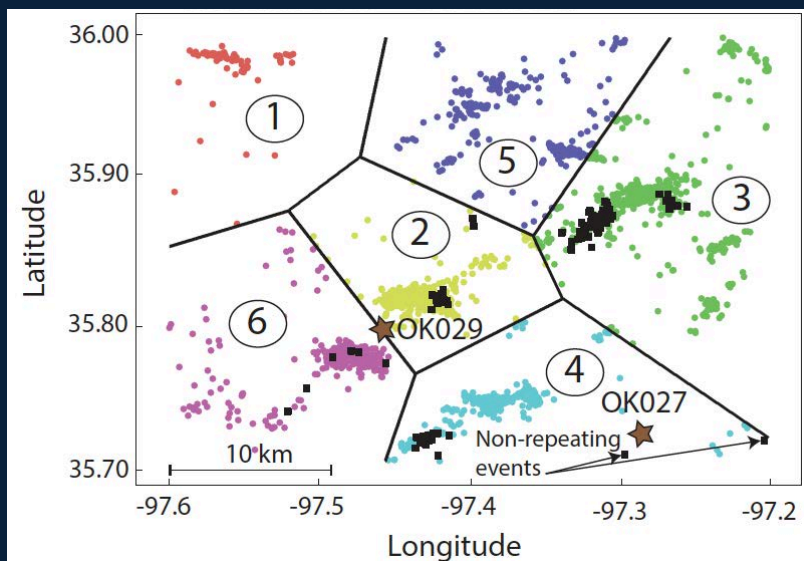


Deep Learning Detection and Location



Deep Learning Detection and Location

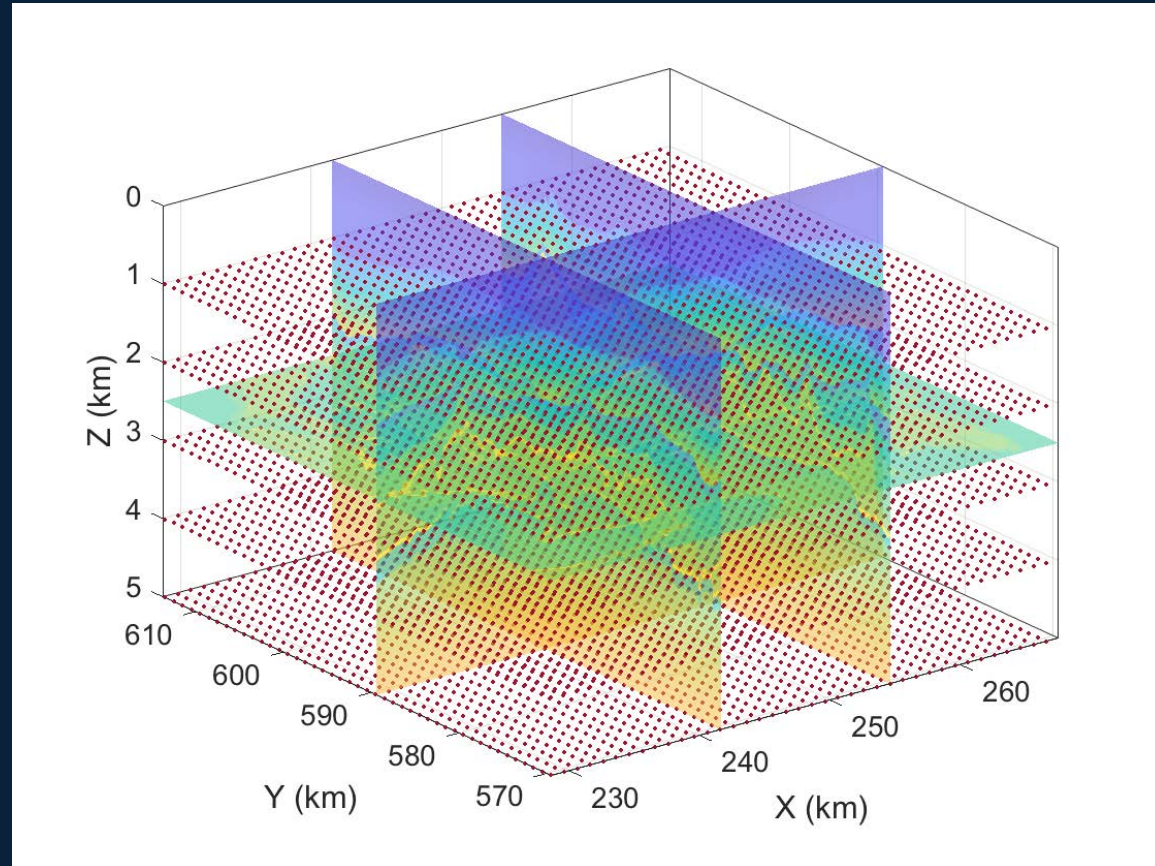
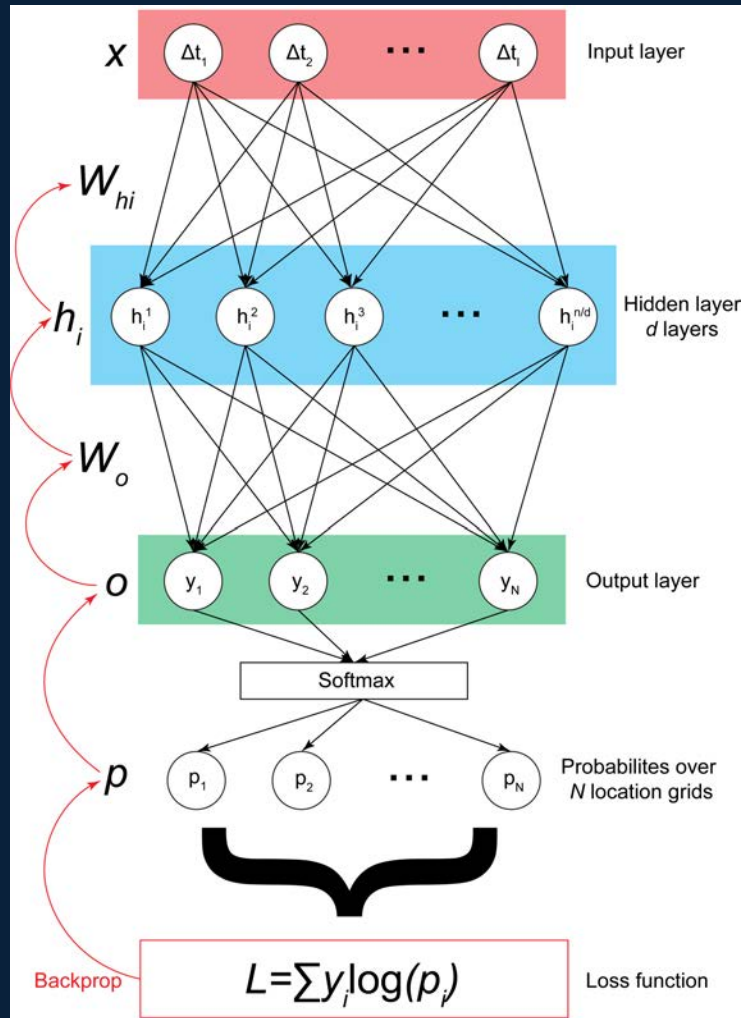
| | Autocorrelation | FAST | ConvNetQuake (ours) |
|--------------------------|-----------------|-----------------|---------------------|
| Noise detection accuracy | 100 % | ≈ 100 % | 99.9 % |
| Event detection accuracy | 100 % | 87.5 % | 100 % |
| Event location accuracy | N/A | N/A | 74.6 % |
| Runtime | 9 days 13 hours | 48 min | 1 min 1 sec |



What we can improve:
1. Location resolution.
2. Use multi-station data.

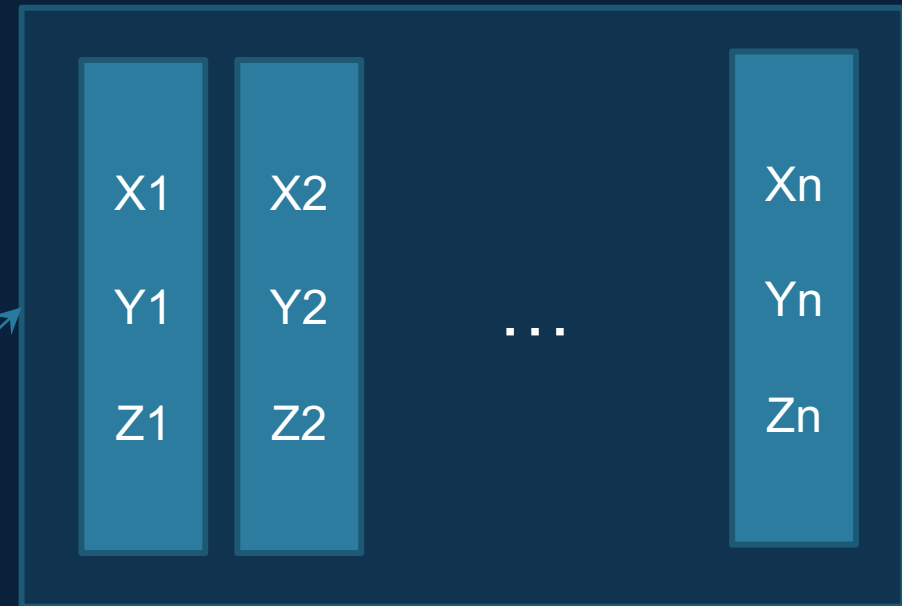
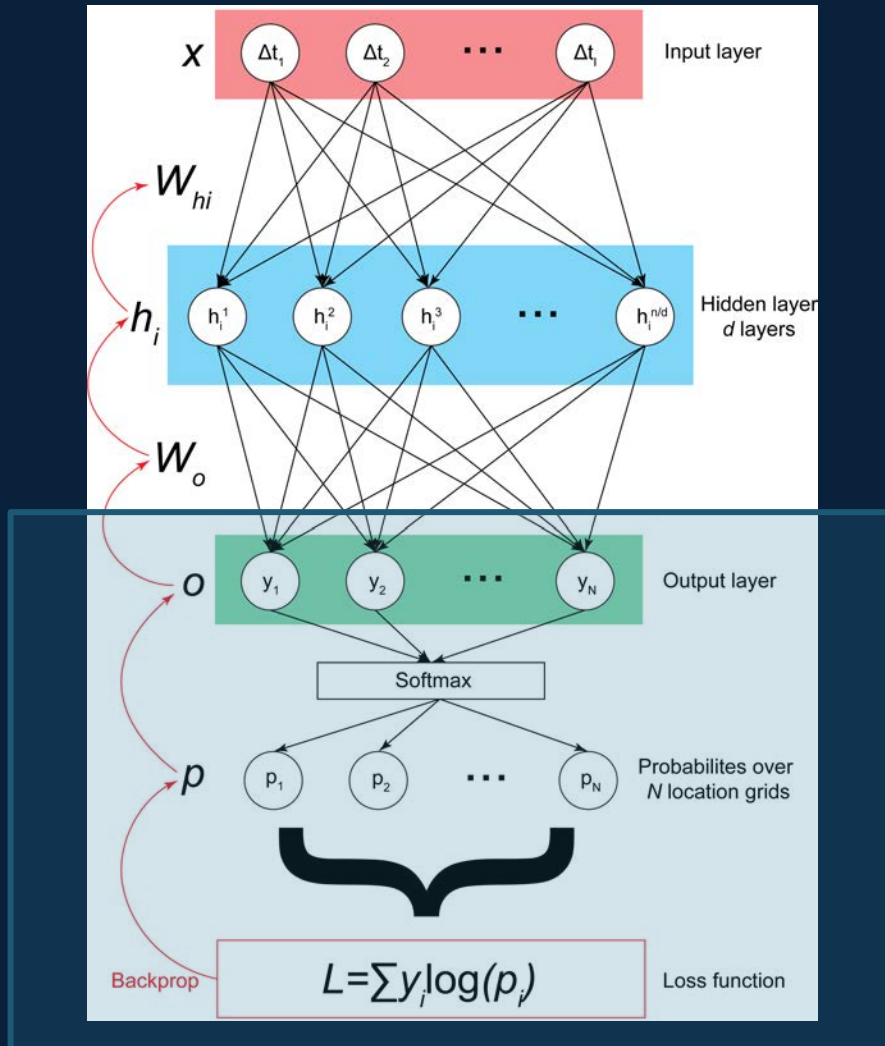
Perol et al., *Sci. Adv.*, 2018

Upgraded 3-D Location in Groningen



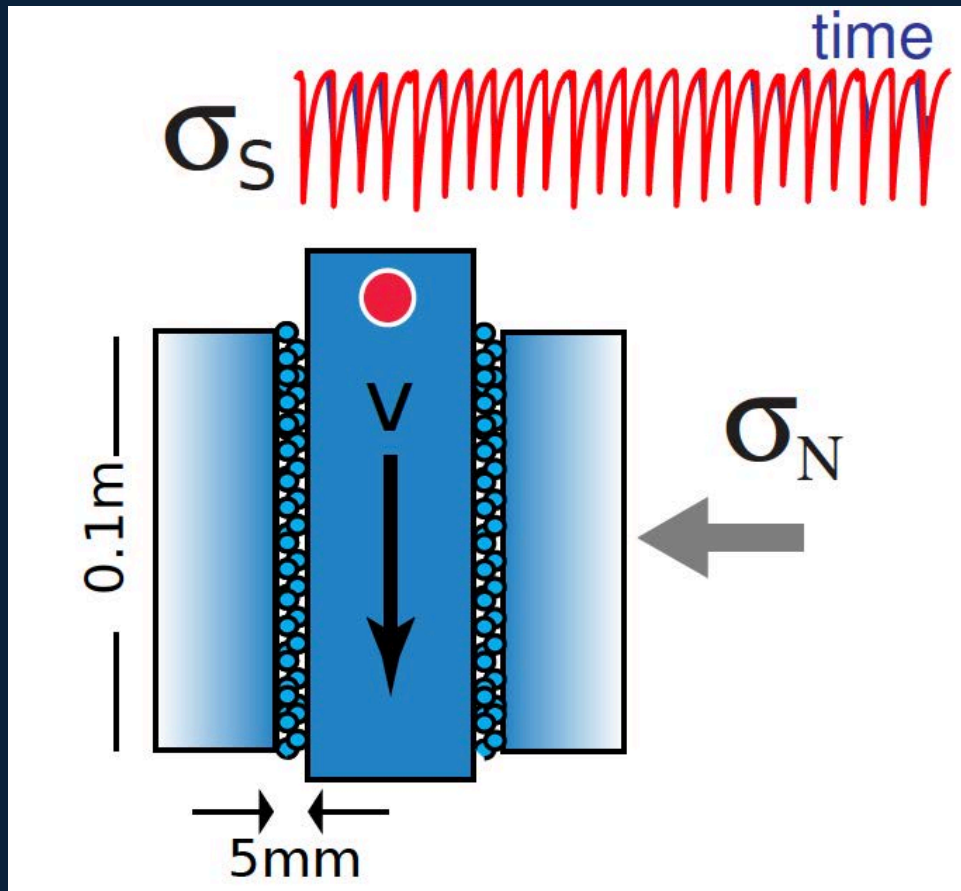
Gu et al., SEG expanded abstract, 2018

Beyond Classification

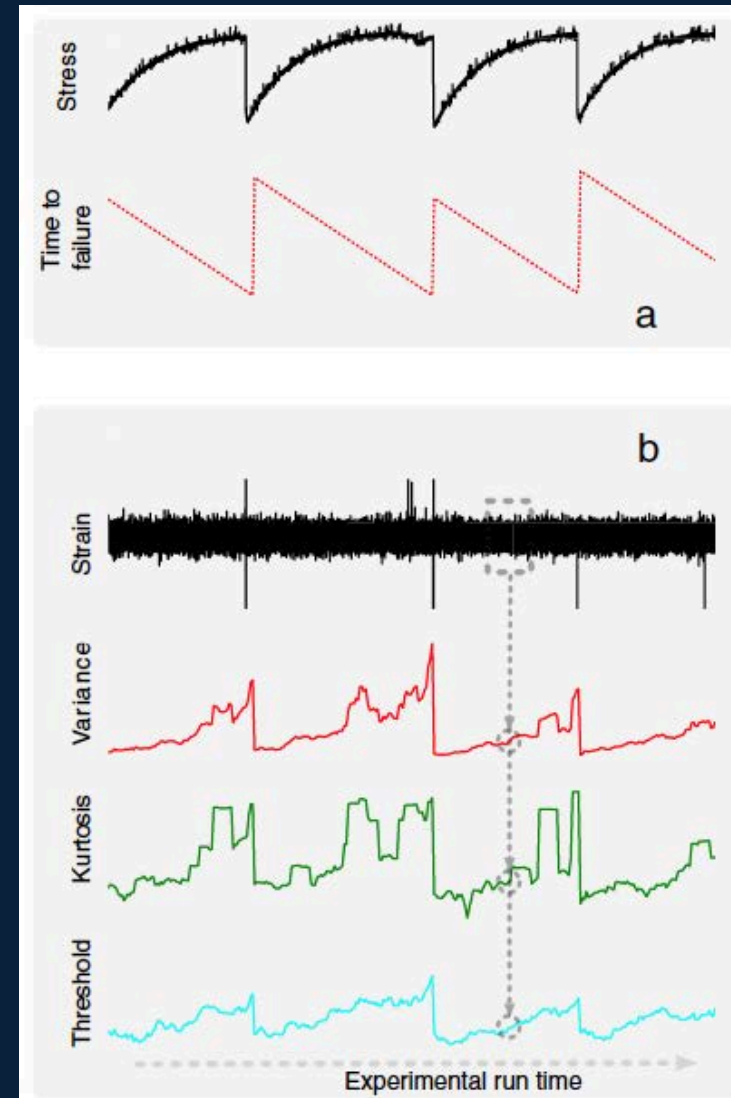


Earthquake Prediction

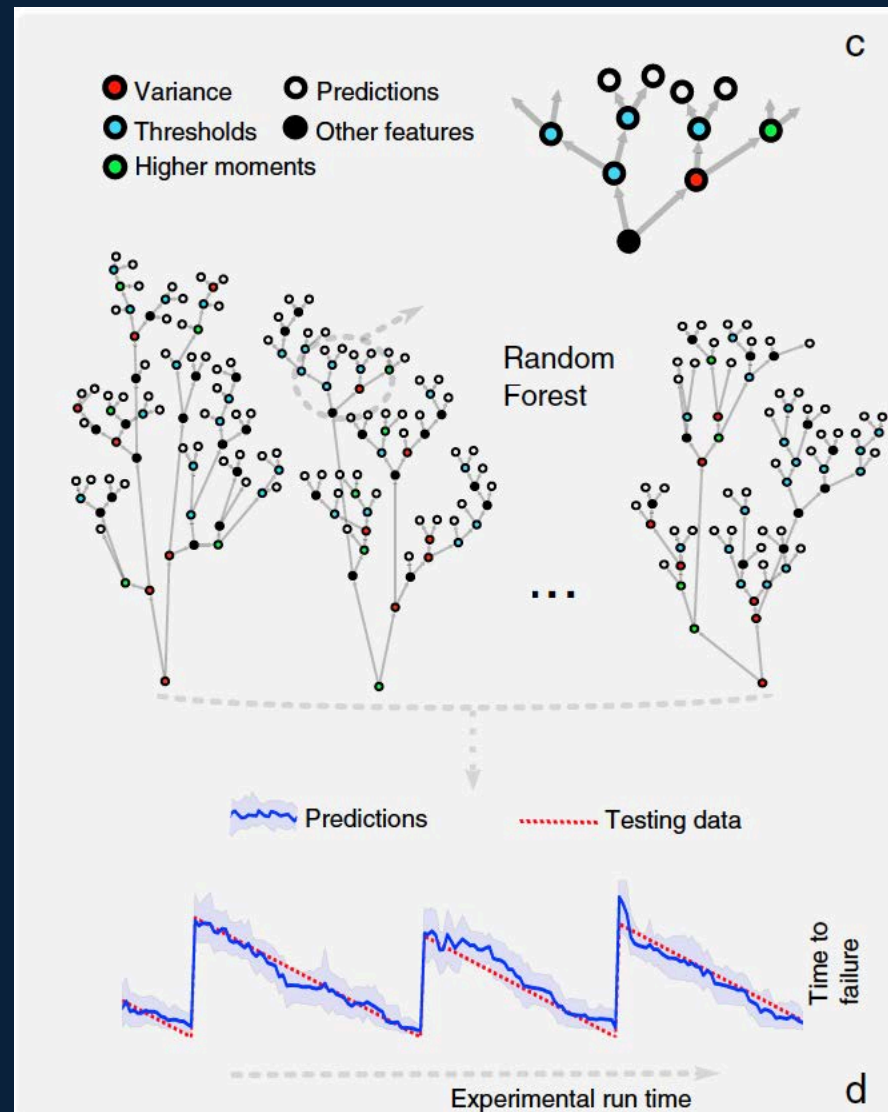
Bi-axial Stick-Slip Experiment



Rouet-Leduc et al., 2017

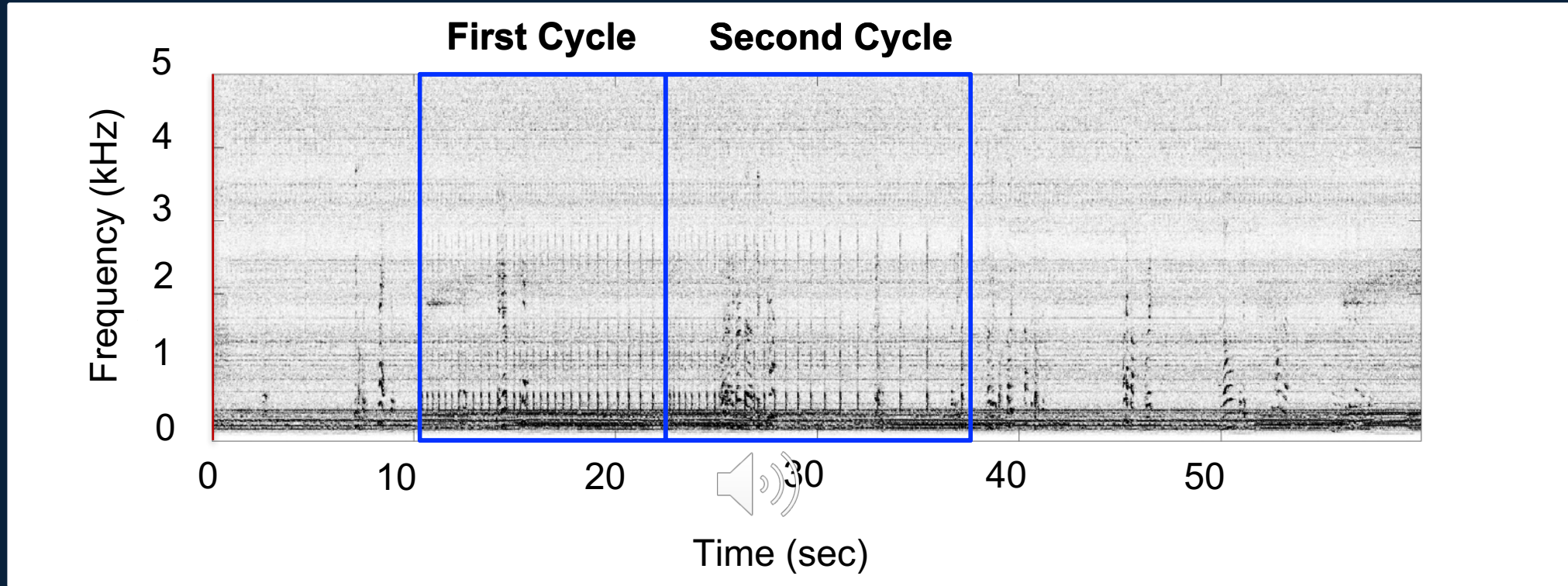
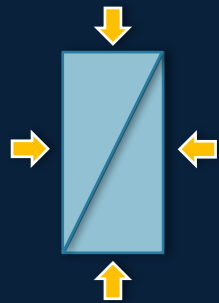


Earthquake Prediction



Rouet-Leduc et al., 2017

Earthquake Forecasting



This Experiment is conducted by Saied Mighani at the rock physics lab.

Conclusion

- The traditional geophysical algorithm becomes costly and impractical with the huge increase of data, both in oil/gas fields and laboratories.
- The big volume of labeled micro-seismic and pico-seismic (laboratory) data makes it possible to apply deep learning to earthquake detection, location and forecasting problems more efficiently and smartly.

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MIT EARTH RESOURCES LABORATORY
ANNUAL FOUNDING MEMBERS MEETING 2018



| **Thank you!**

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