

Elastic full waveform inversion with extrapolated low frequency data

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[EARTH, ATMOSPHERIC AND PLANETARY SCIENCES]

Motivation: elastic full waveform inversion

Why elastic FWI

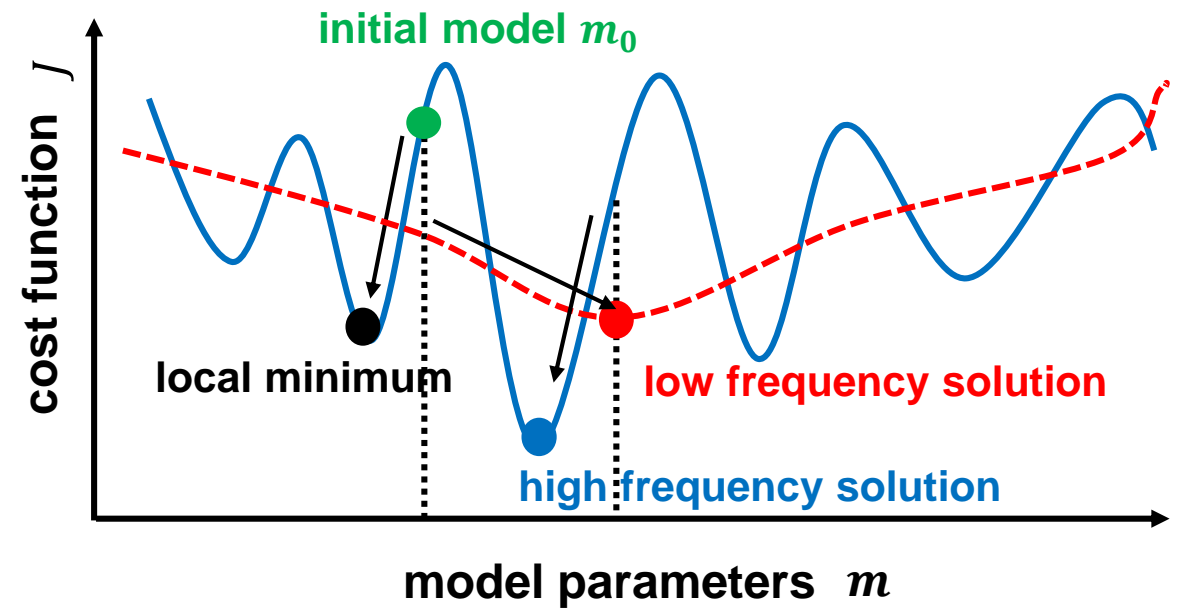
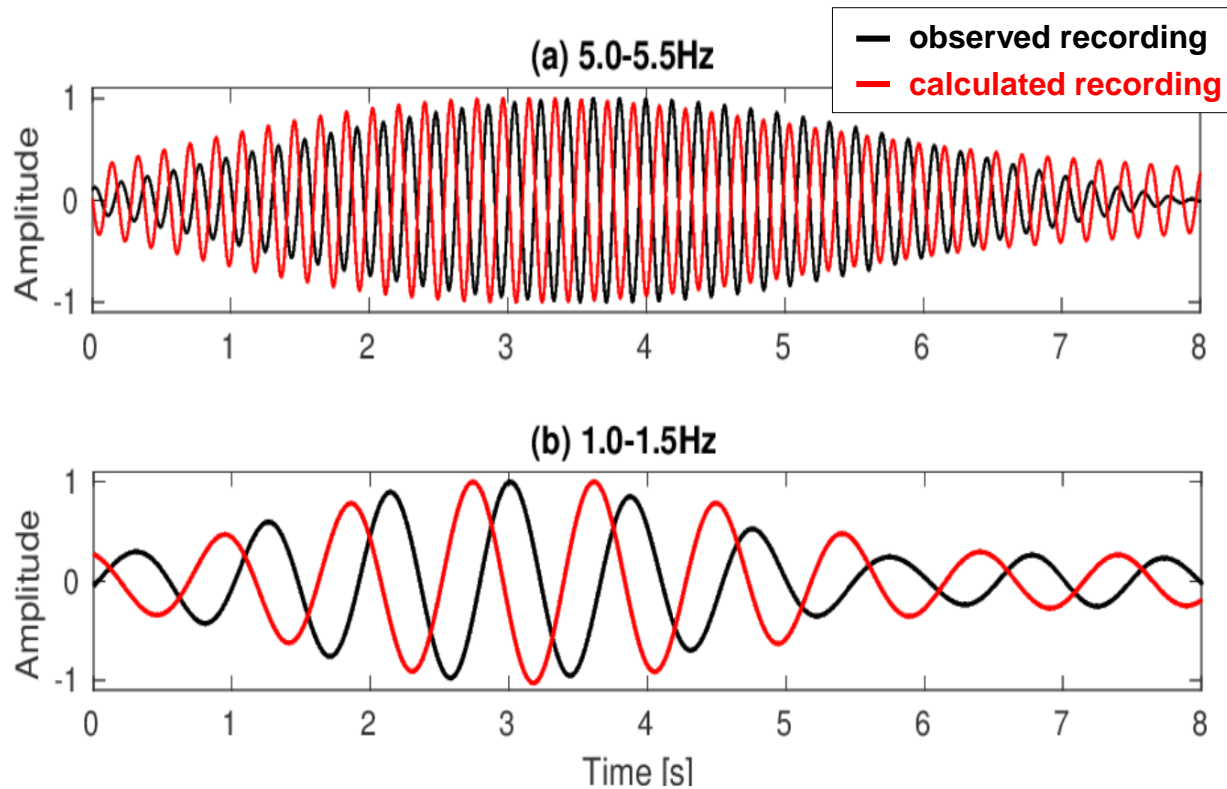
- strong elastic effects;
- reservoir characterization;
- near-surface investigations;
- ...

How (Tarantola, 1986; Mora, 1987; Köhn et al., 2012)

$$J = \frac{1}{2} \delta \mathbf{d}^T \delta \mathbf{d} = \frac{1}{2} \sum_s \sum_r \int [\underbrace{\mathbf{u}_{cal}}_{v_x \ v_y} - \underbrace{\mathbf{u}_{obs}}_{v_x \ v_y}]^2 dt$$

$$\mathbf{m}_{k+1} = \mathbf{m}_k - \mu_k \left(\frac{\partial J}{\partial \mathbf{m}} \right)_k \longrightarrow \mathbf{m}: v_p, v_s, \rho$$

Motivation: cycle-skipping



Cycle-skipping is more severe in elastic FWI compared to acoustic FWI, due to the short S-wave wavelength.

Motivation: elastic full waveform inversion

Cycle-skipping is more severe in elastic FWI and requires lower starting frequency.

Synthetic data studies:

	name of benchmark model	starting model	starting frequency
Brossier et al., 2009	Overthrust	Gaussian smoothing	1.7Hz
Brossier et al., 2010	Valhall	Gaussian smoothing	2.0Hz
Choi et al., 2008	Marmousi2	velocity-gradient	0.16Hz
Köhn et al., 2012	Marmousi2	velocity-gradient	0-2Hz
Jeong et al., 2012	Marmousi2	velocity-gradient	0.12Hz

Field data studies: lack of low frequencies

Crase et al., 1990; Sears et al., 2010; Vigh et al., 2014; Raknes et al., 2015; Marjanović et al., 2018; Borisov et al., 2020, etc.

Method: bandwidth extension with deep learning

- **Deep neural networks (DNN):**

$$\mathbf{y} = f(\mathbf{x}, \mathbf{w}) = f_L(\dots f_2(f_1(\mathbf{x})))$$

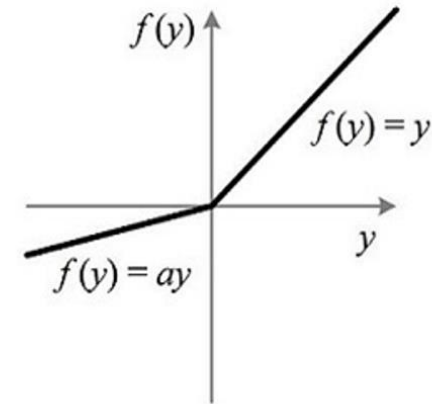
where:

- \mathbf{x} : seismograms bandlimited to high frequencies
- \mathbf{y} : the same seismograms bandlimited to low frequencies
- \mathbf{w} : parameters of DNN to be learned

- **Training:** learning \mathbf{w} with known \mathbf{y}

$$J(\mathbf{w}) = \frac{1}{m} \sum_{i=1}^m L(y_i, f(x_i, \mathbf{w}))$$

- **Test (predict):** $f(\mathbf{x}, \mathbf{w})$



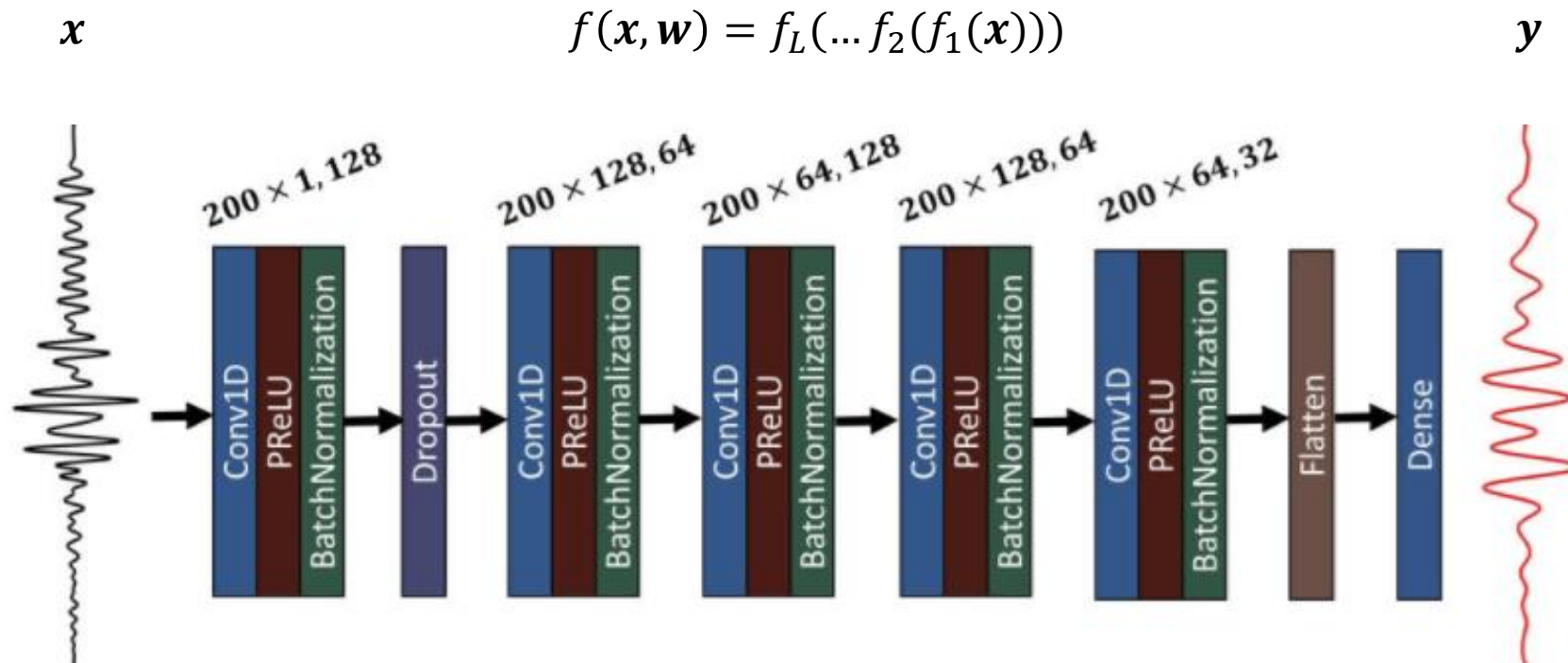
$$PReLU(x_i) = \begin{cases} x_i & \text{if } x_i > 0 \\ a_i x_i & \text{if } x_i \leq 0 \end{cases}$$

- **Optimizer:** Adam (Kingma and Ba, 2014)

(Sun and Demanet, 2018)

Method: architecture of convolutional neural networks

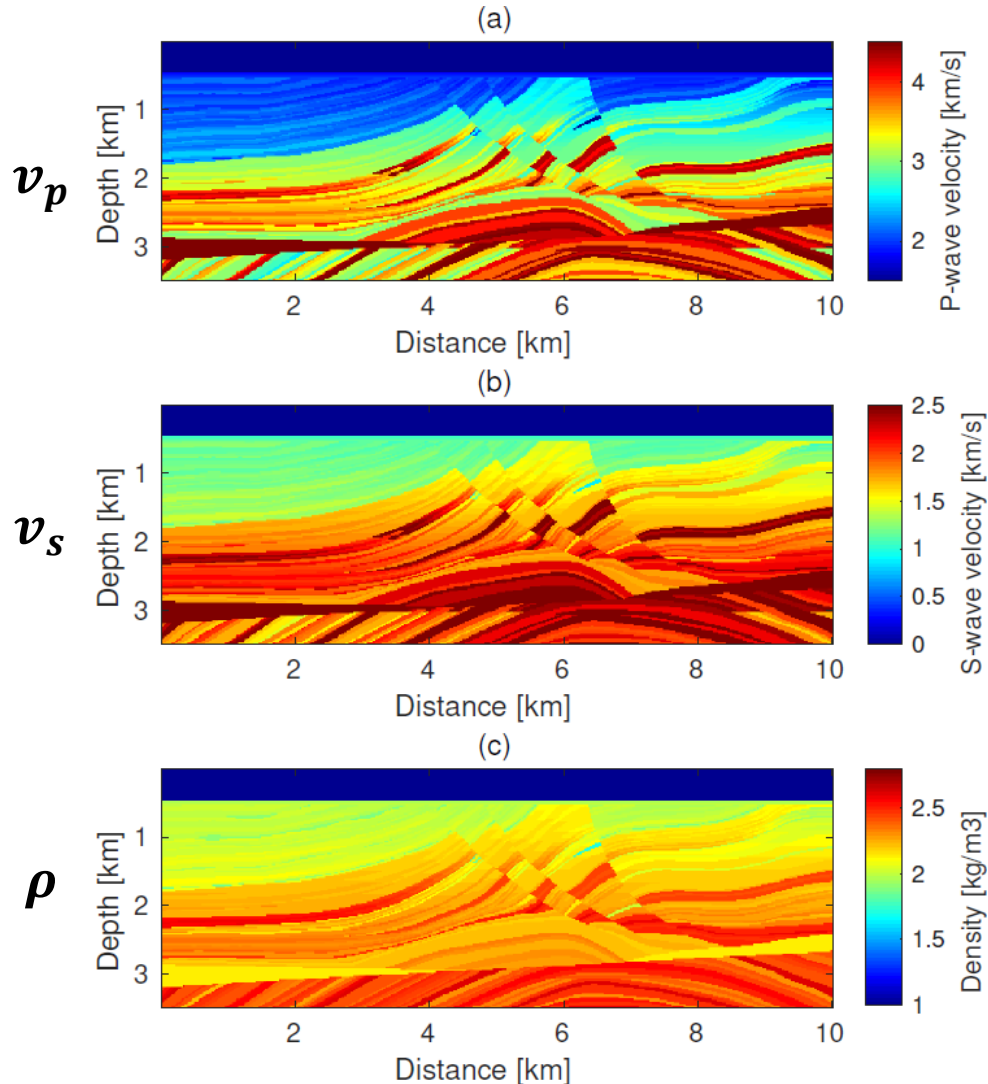
A large receptive field is achieved by **directly using a large filter**:



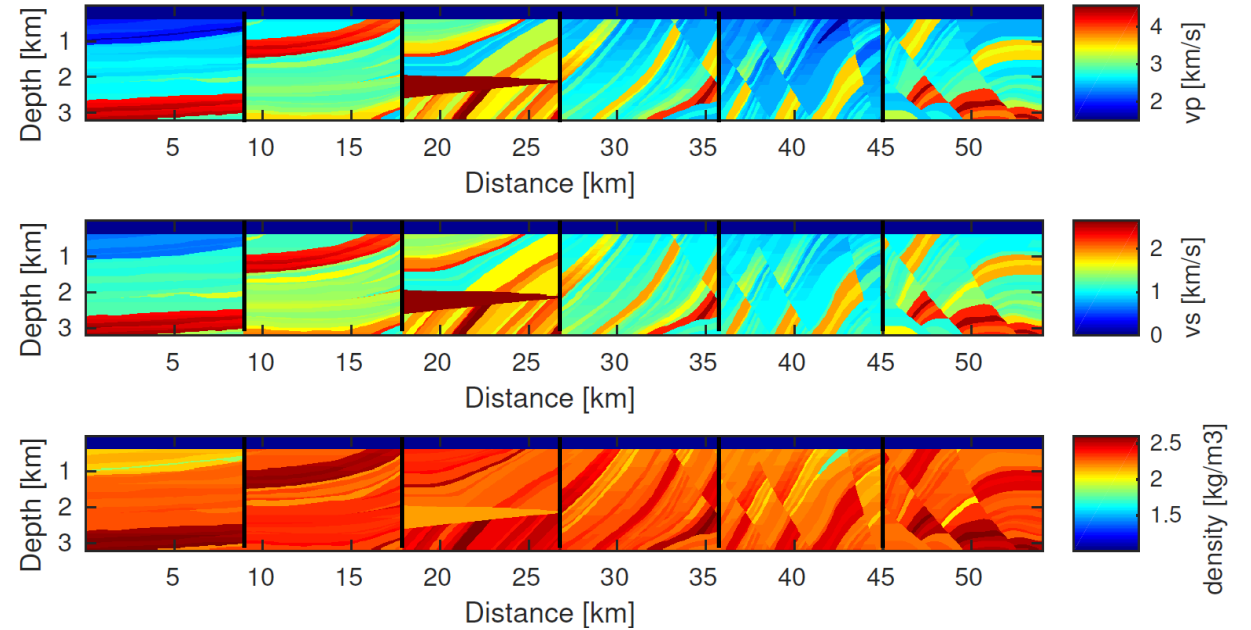
(Sun and Demanet, 2020)

Method: training and test datasets

Test model: unknown low frequencies



Training model: known low frequencies

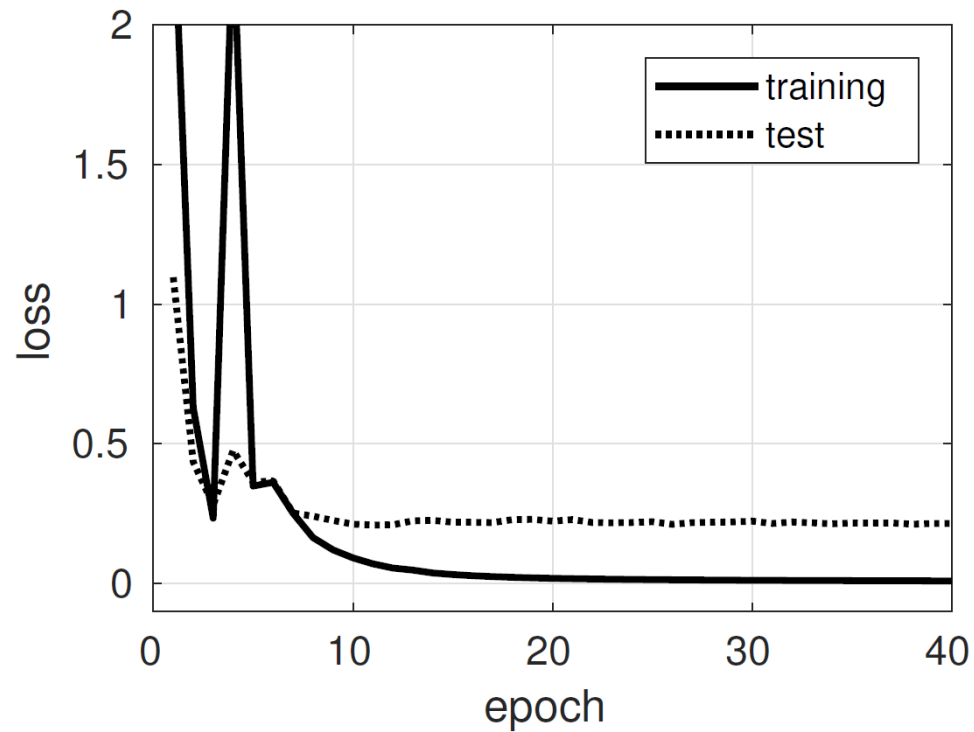


- **horizontal component v_x**
training dataset: 6 models \times 100 shots \times 400 receivers
test dataset: 1 models \times 50 shots \times 400 receivers
- **vertical component v_y**
training dataset: 6 models \times 100 shots \times 400 receivers
test dataset: 1 models \times 50 shots \times 400 receivers

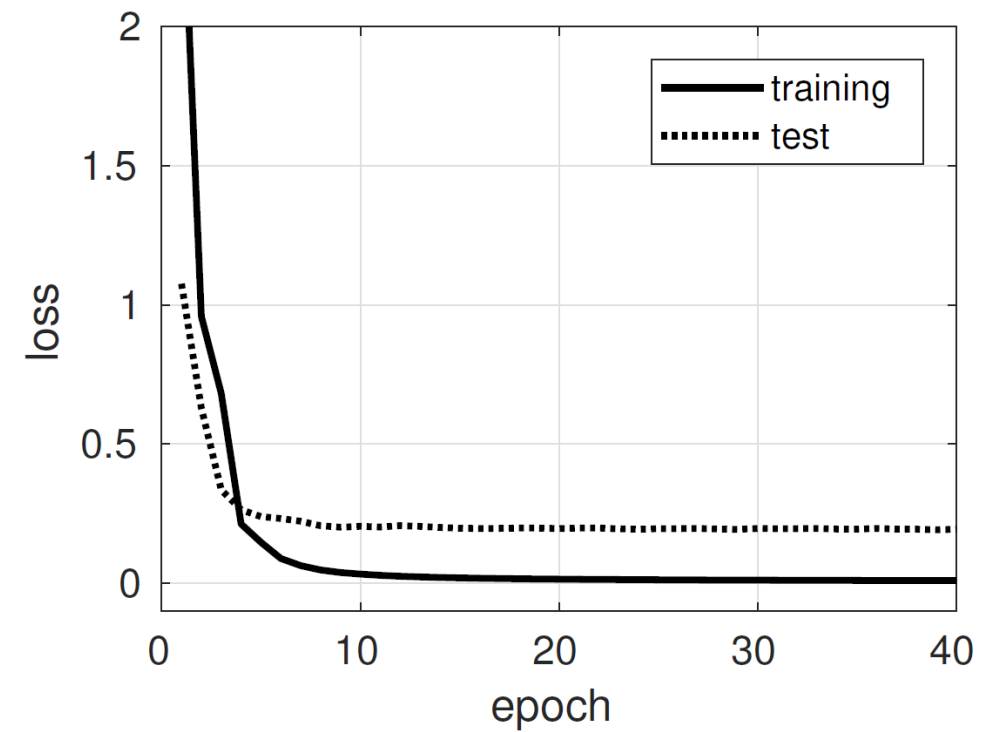
Low frequency extrapolation of multicomponent data

Extrapolate **0.1 - 5Hz** low frequency data from **5 - 25Hz** bandlimited data using ARCH1

horizontal component (v_x)

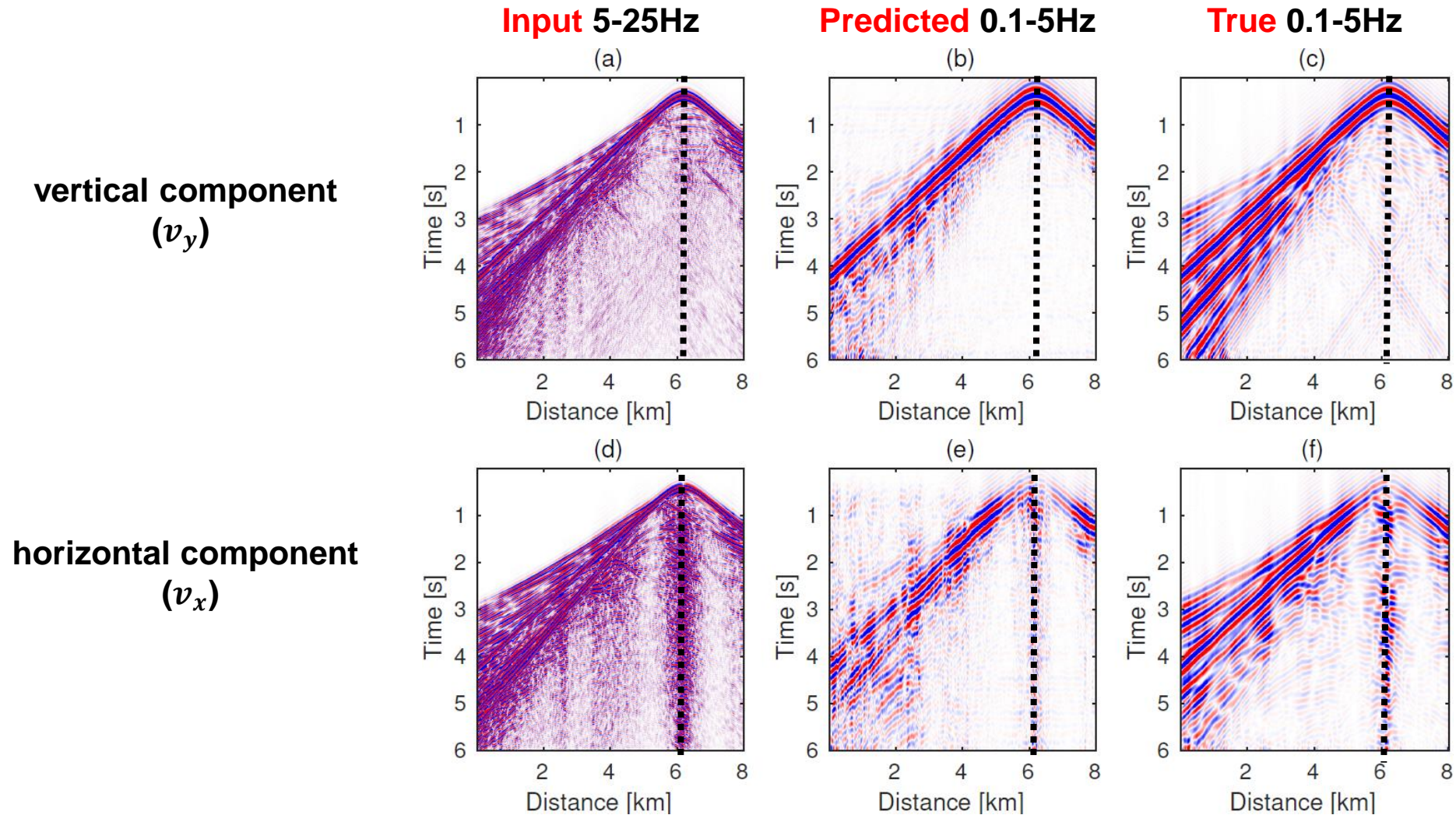


vertical component (v_y)



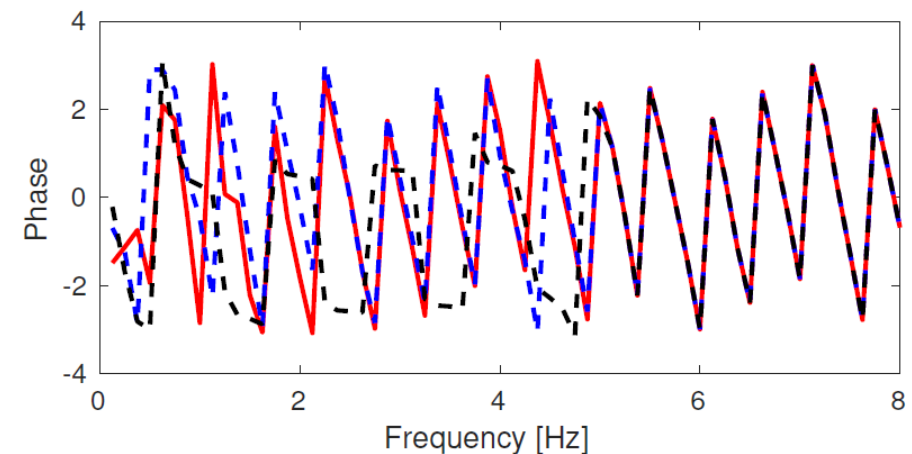
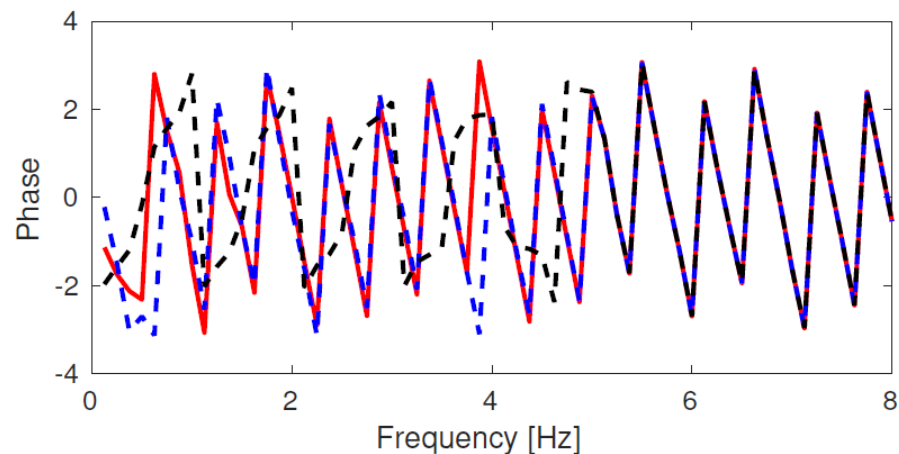
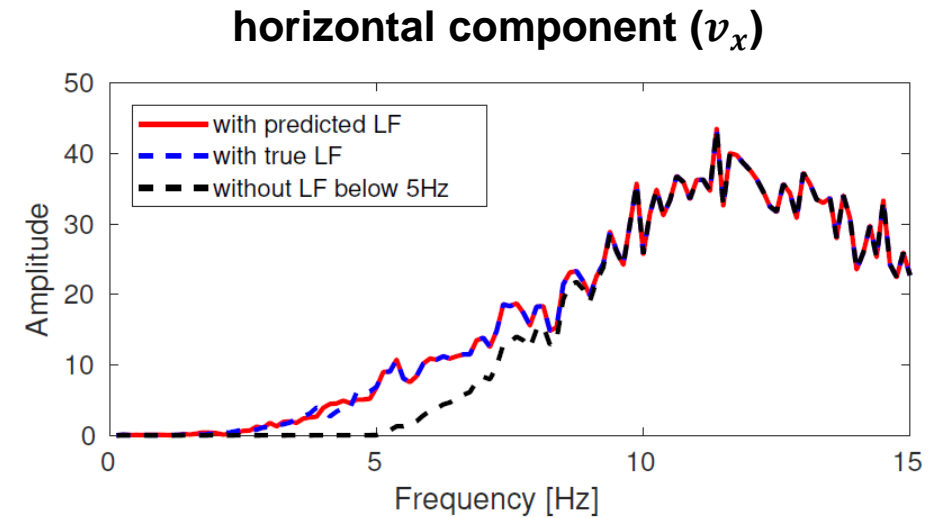
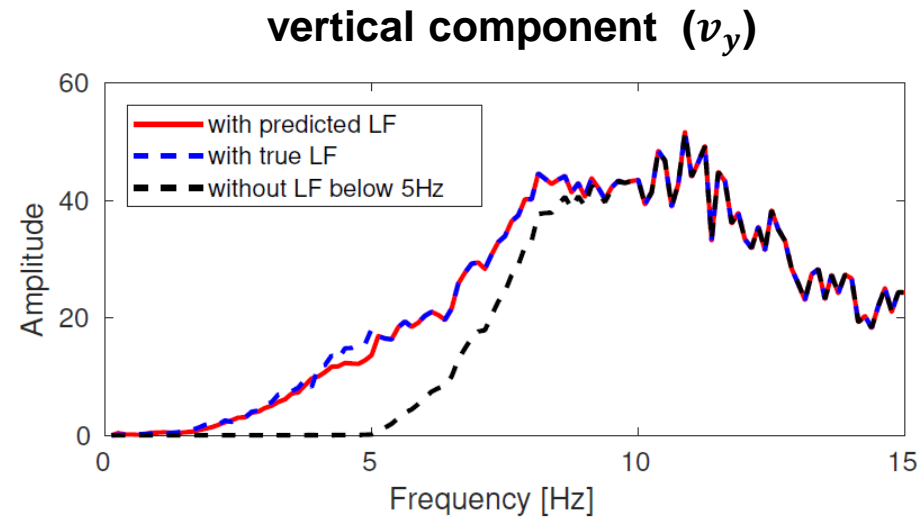
Low frequency extrapolation of multicomponent data

Extrapolation results of ARCH1 **trained on elastic data**



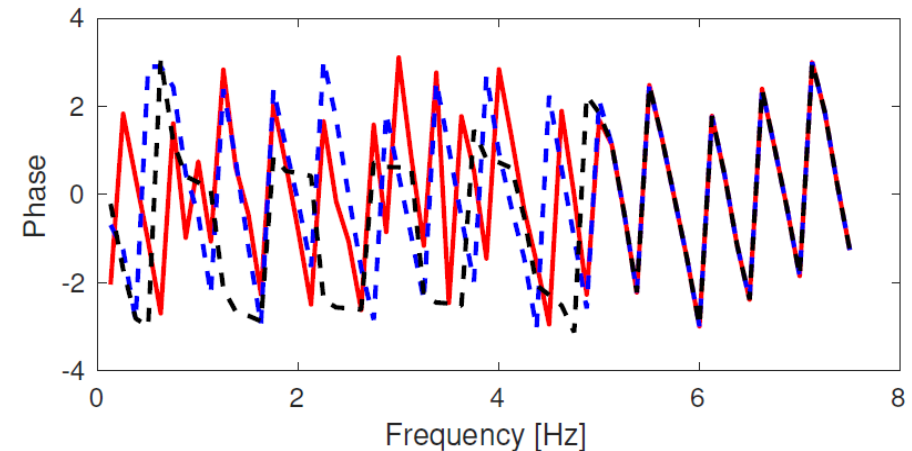
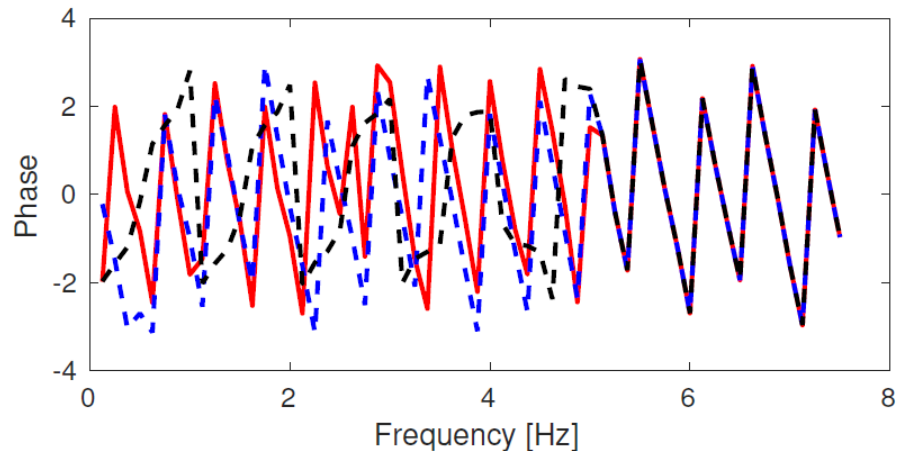
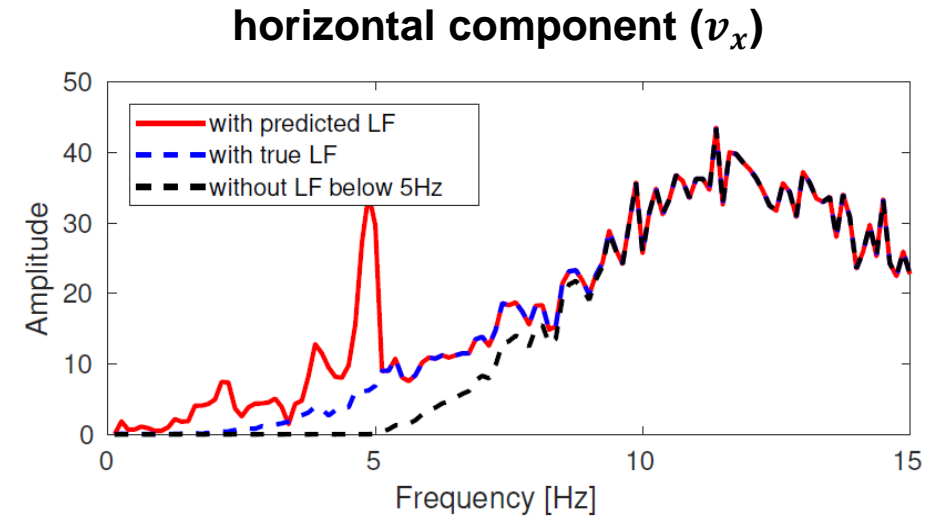
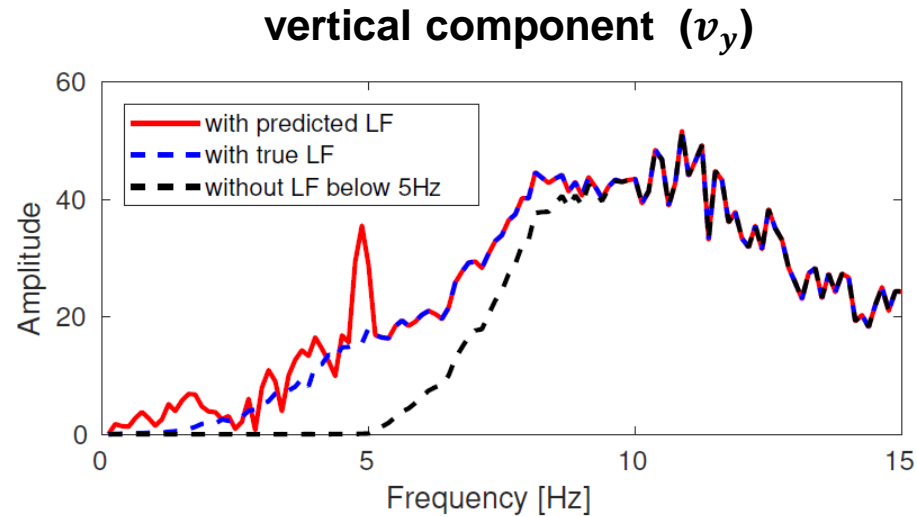
Low frequency extrapolation of multicomponent data

Extrapolation results of ARCH1 **trained on elastic data**



Generalization over physical models

Extrapolation results of ARCH1 **trained on acoustic data**

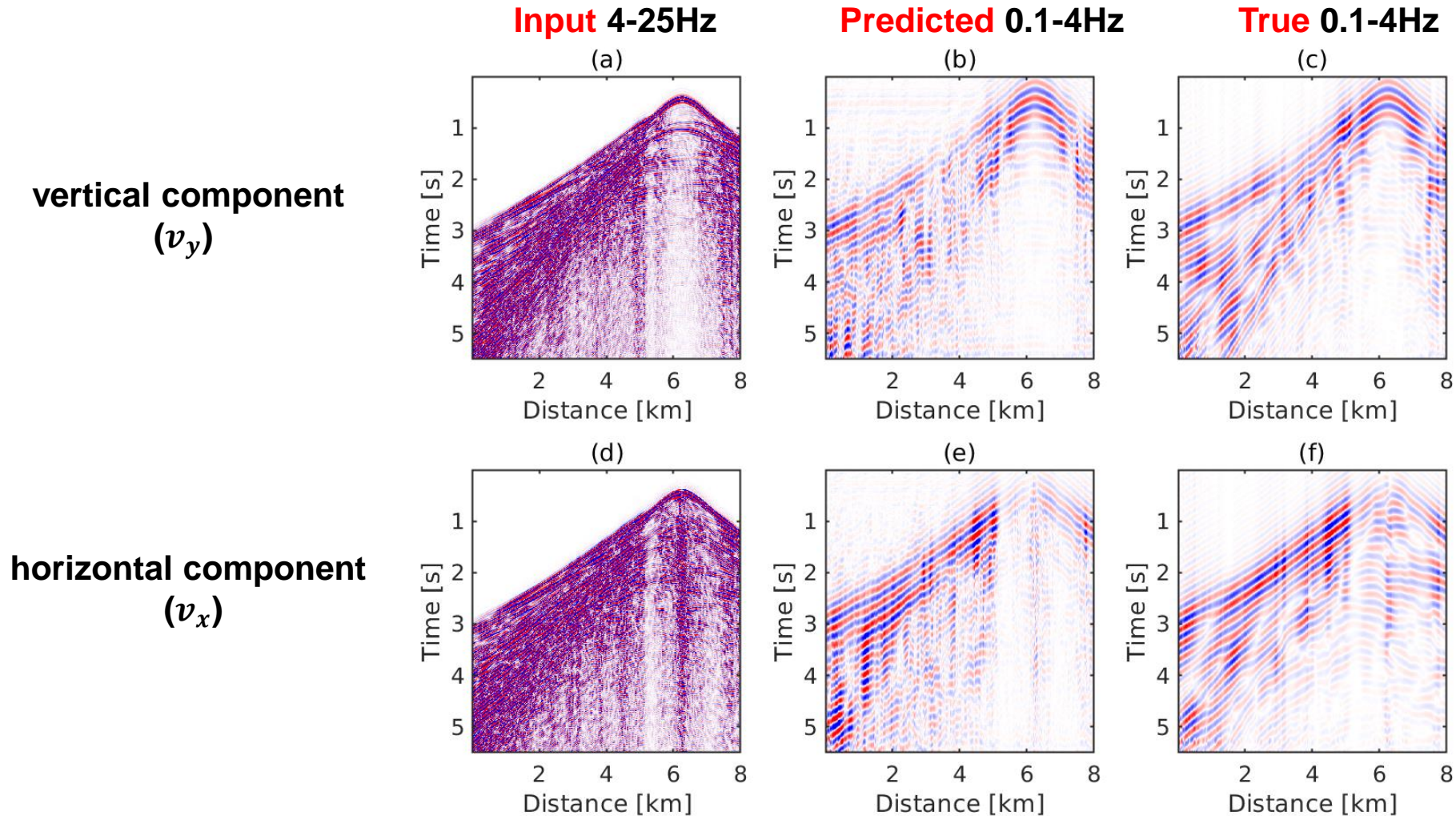


Extrapolated elastic FWI

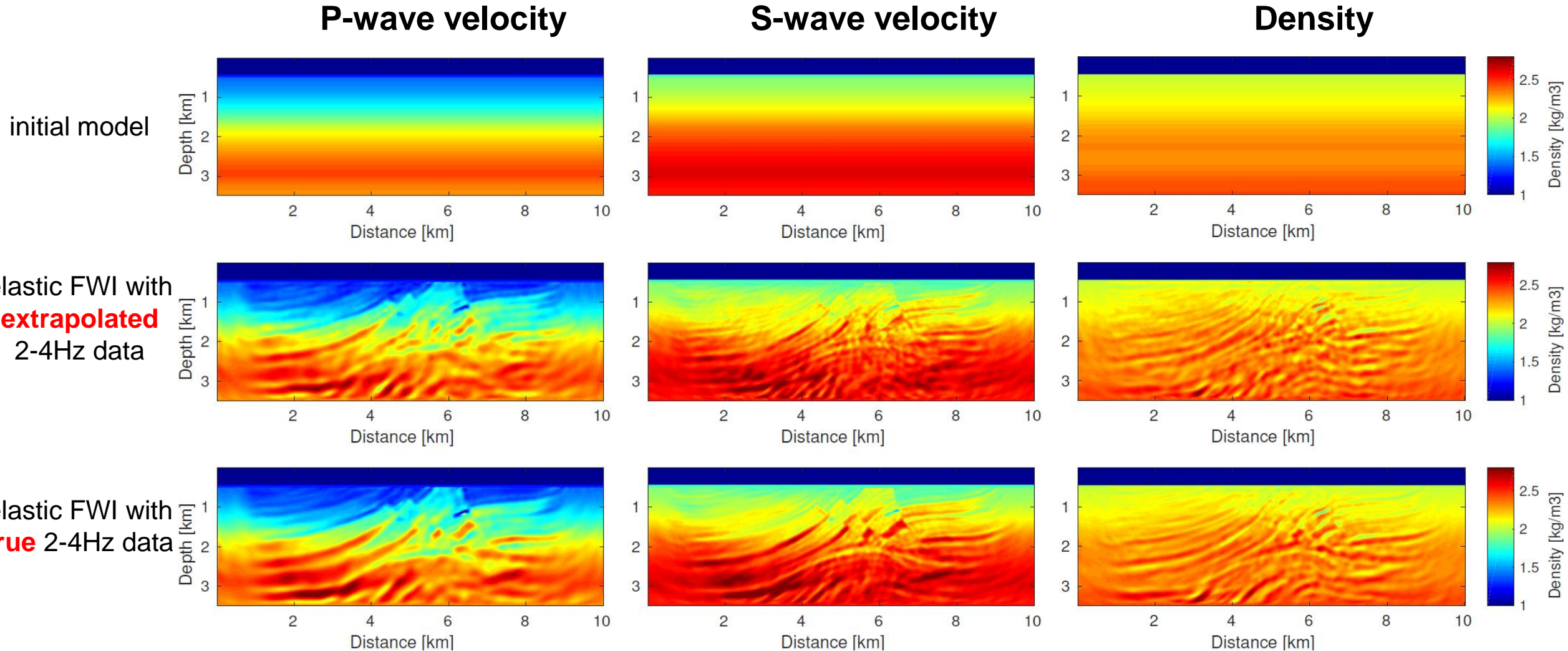
- source: Ricker wavelet with a dominant frequency of 10Hz;
- extrapolate 0.1-4Hz low frequency data from 4-25Hz bandlimited data using ARCH1 (the lower band of the bandlimited data is 4Hz);
- a free surface condition is applied to the top of models (multiples in training and test datasets);
- multi-scale FWI: 2-4Hz, 4-6Hz, 4-10Hz and 4-20Hz (Bunks et al., 1995);
- optimizer: L-BFGS with 30 iterations in each frequency band;

Extrapolated elastic FWI

Extrapolation results of ARCH1 **trained on elastic data with multiples**



Elastic FWI using **2-4Hz low frequency** data



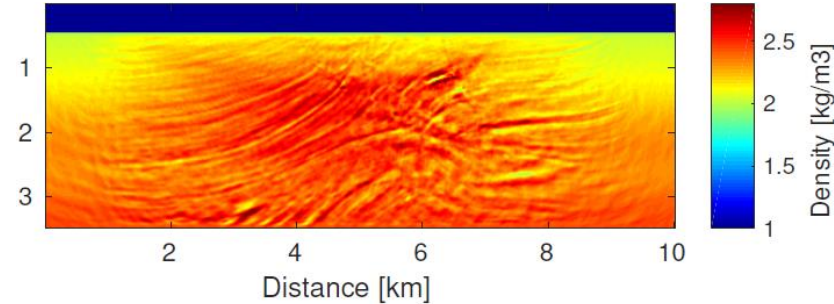
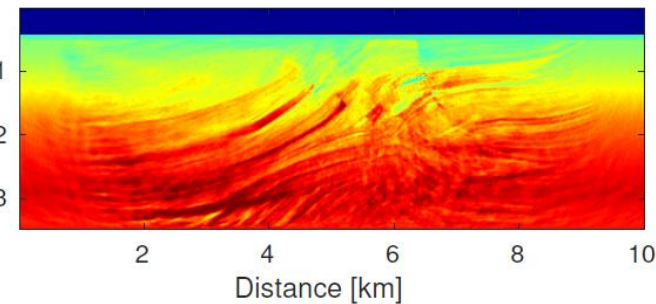
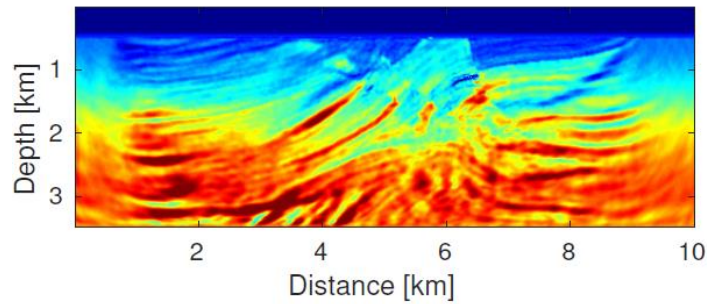
Elastic FWI continued with 4-20Hz bandlimited data

P-wave velocity

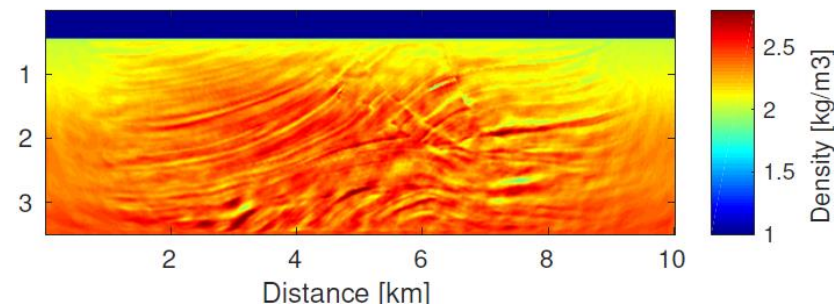
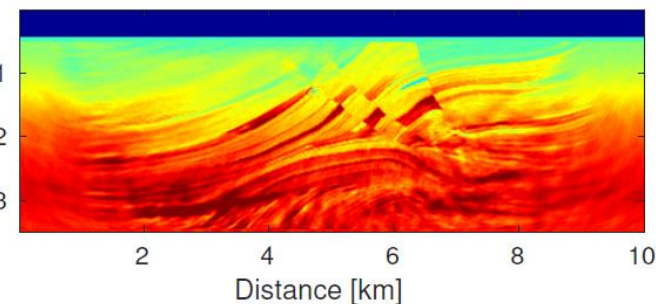
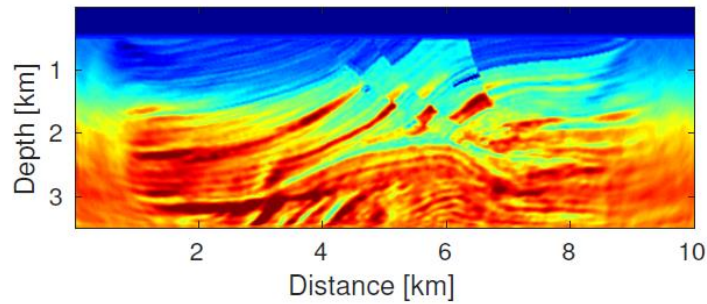
S-wave velocity

Density

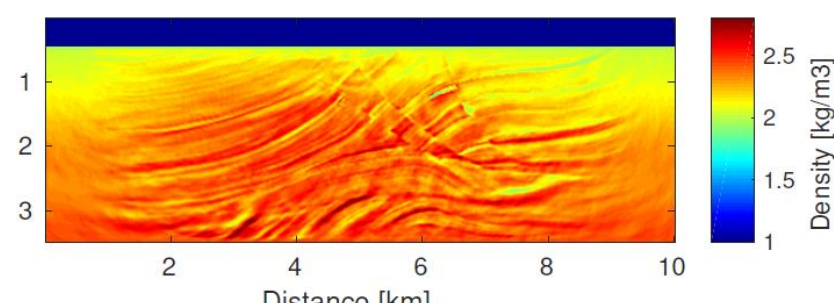
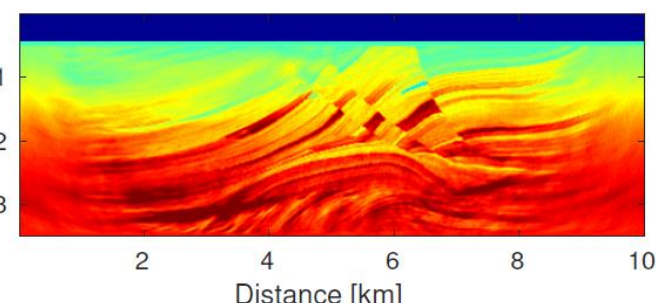
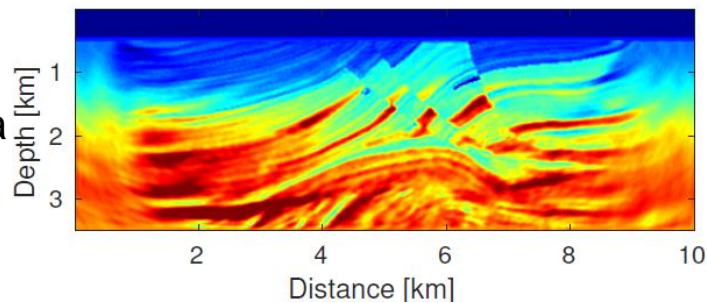
started from initial model



started from **extrapolated** 2-4Hz data



started from **true** 2-4Hz data



- The deep learning model is designed with a large receptive field by directly using a large filter on each convolutional layers.
- By training the neural network twice, once with a dataset of horizontal components and once with a dataset of vertical components, we can extrapolate the low frequencies of multi-component band-limited recordings separately.
- The accuracy of the extrapolated low frequencies is enough to provide low-wavenumber starting models for elastic FWI of P-wave and S-wave velocities using band-limited data above 4Hz.
- The neural network trained on purely acoustic data shows larger prediction error on elastic test dataset compared to the neural network trained on elastic data.

Limitations

- Although the accuracy of extrapolated low frequency data is sufficient for elastic FWI of P-wave and S-wave velocities started from 4Hz band-limited data, challenges remain to enable the neural network to work for the data band-limited above 4Hz.
- Starting from the 2-4Hz extrapolated data, the inversion of density model still suffers from the cycle-skipping problem and lack of the low-wavenumber structures.
- In addition to the wave propagation driven by different physics, another factor that makes the generalization fail could be numerical modeling.
- The source signal is assumed to be known for extrapolated elastic FWI.
- The absence of a physical interpretation for the operations performed by the network.

Acknowledgements

- Tensorflow (Abadi et al., 2015) and Keras (Chollet et al., 2015) are used for deep learning.
- Elastic FWI is implemented using the open source code DENISE (<https://github.com/daniel-koehn/DENISE-Black-Edition>).
- Acoustic training datasets are simulated using Pysit (Hewett & Demanet, 2013).

- **Thanks to MIT ERL and Total S A for support.**
- **Thanks for your attention.**

Questions and Comments?